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220 MHz . To get away from the crowd, ICOM has the IC-3AT $220.000-224.990 \mathrm{MHz}$ handheld with 1.5 watts output, thumbwheel selection and a DTMF pad.

440 MHz . For 440 MHz operation, ICOM has two handhelds available, the versatile IC-04AT and the IC-4AT. The IC-04AT and IC-4AT offer full coverage from $440.000-449.995 \mathrm{MHz}$. The IC-04AT includes an LCD readout, 32 PL tones standard, DTMF direct keyboard entry, three watts output, (optional 5 watts output with IC-BP7 battery pack), 10 memories and three scanning systems. The IC-4AT has a DTMF pad, thumbwheel selection and 1.5 watts output.
1.2 GHz . ICOM announces the IC-12AT $1260.000-1299.990 \mathrm{MHz}$ handheld, the first 1.2 GHz handheld available. The IC-12AT features 10 memories, an LCD readout, DTMF direct keyboard entry, two scanning systems and one watt output.

Accessories. A variety of interchangeable accessories are available, including the IC-BP8 800 mAH long-life battery pack, HS-10 boom headset, CPI cigarette lighter plug and cord, HM9 speaker mic (for IC-02AT, IC-04AT and IC-12AT), leather cases, and an assortment of battery pack chargers.

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## TS-940S

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- 100\% duty cycle transmitter. Super efficient cooling system using special air ducting works with the inter nal heavy-duty power supply to allow continuous transmission at full power output for periods exceeding one hour. - High stability, dual digital VFOs. An optical encoder and the flywheel VFO knob give the TS-940S a positive tuning "feel."
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Specifations and prices ate subuect ! shange without notice ot otitrgatron


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## ham

## radio magazine

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## specs in secs: an idea whose time has come

What's smaller than a bread box, lighter than a Bic pen, faster than a speeding bullet, and of interest to thousands of Radio Amateurs (or least it will be)?

You guessed it. It's Motorola's solution to our transistor specification problem, all on a single floppy disk. Appropriately labeled Specs in Secs, that's exactly what you get when you load it into your IBM PC-compatible computer.

In the program, Motorola has provided device information for over 1600 bipolar power transistors and TMOS ${ }^{\text {TM }}$ Power MOSFETs, and included a user-friendly method of retrieving the data as well. It's not only extremely useful, but also fun to use. And because of its flexibility, you feel like you're making real design decisions - and you are!

Did I just hear someone say "Now just hold on one dang minute! We're Radio Amateurs, not engineers. Why do we need this information, anyway?"

I'm really glad you asked. First of all, some of us are engineers or technicians, in addition to being licensed Radio Amateurs. And even if you're not an engineer or a technician, I'm willing to bet that sometime in your Ham career you've designed some circuit, or at least wished that you could have. Specs in Secs won't do the circuit design for you (although there are software programs out there that will). What it will do is, through a few keystrokes, provide parts choices in seconds.
"Great!" you say, with a little bit of sarcasm. Now you have 1600 or so power device specifications. But like most other Radio Amateurs, you're interested in rf circuits - oscillators, preamplifiers, etc. Well, don't sell a power device short before you look at its specifications - $f_{T}$, for example, which is related to maximum frequency of operation. Some of these power devices provide real gain at frequencies that are of interest to us.

Without dwelling on this point, let me mention that Motorola indicated in the brochure that accompanied this diskette that they're working on entering their entire semiconductor product line on a single 360 K floppy disk, and that takes time. I should know; I've done something similar with my compendium of Amateur Radio article references, From Beverages Thru OSCAR - A Bibliography (November 1980), and that only took me six years and eight diskettes, and I'm almost finished!
"But is Specs in Secs easy to use?" you ask.
It couldn't be simpler. You place the disk in any drive, type the letter $M$ (Enter), and away you go. A menu provides a number of choices, including, in essence, an on-screen manual. Actually, the first thing you see is a "Start-up Screen" with a carefully chosen set of choices (defaults) that you'll probably want anyway.

Here's where it really becomes useful. Selection "D" is called "Parametric Search." With this choice, you're given the opportunity not only to choose the important parameters, but their order and value as well. The more specific you are, the more quickly you'll arrive at the appropriate component. Motorola does, however, recommend that you also have the hard copy (selection guide) available for the final decisionmaking process.
If you're reasonably sure of the component you want to use, just enter its part number after pressing Selection "C," appropriately labeled "Part Number Search." If it can't be found, you won't be hit over the head or knocked out of your chair by a loud noise. The program will just quietly tell you that it can't find that particular part number. Believe me, you still have many other choices.
I could easily go on about its other features, but for $\$ 2$ you can get your own copy and see for yourself. By the way, Parlez-vous Francais? Or German, Spanish, or Italian? The on-screen manual is written in these other languages as well, and you can print all of them out and have a copy at your side.

For your copy of Specs in Secs (DK101/D), send a check or money order for \$2 to Motorola Semiconductor Products, Literature Distribution Center, P.O. Box 20924, Phoenix, Arizona 85063.

Rich Rosen. K2RR Editor-in-Chief

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Dean LeMon, KR0V sure is! Dean got active in Amateur Radio when he was 16 years old and earned his Extra Class license in less than four years! "It's a facinating hobby and a great way to meet all kinds of new people from all over the world."

Dean has cerebral palsy and got started in Amateur Radio with help from the Courage HANDI-HAM System. The HANDI-HAM System is an international organization of able-bodied and disabled hams who help people with physical disabilities expand their world through Amateur Radio. The System matches students with one to one helpers, provides instruction material and support, and loans radio equipment

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Call or write the Courage HANDI-HAM System WOZSW at Courage Center, 3915 Golden Valley Road, Golden Valley, Minnesota 55422, phone (612) 588-0811.

Are you radioACTIVE?


## Dick Smith kits

## Dear HR:

Perhaps you've heard this, but in case not: I just found out that Dick Smith Electronics is no longer doing business in the United States. The Dick Smith kits are now being sold by American Electronics, P.O. Box 301, Greenwood, Indiana 46142.

Joe Moell, K00V
Fullerton, California 92633

## say what you think

Dear HR:
What a delightful guest editorial by Robert Zavrel, Jr., W7SX (September, 1987)! Nearly everything listed was something I could identify with. However, I had to move some of the "don't likes" into the "do likes" column, and vice versa. Not many, but some.

That started me thinking. Wouldn't it be interesting to see how other readers felt? As Bob said in the article, "there comes a time when a guy's got to say what he really thinks!" My mind started wandering. It would be really fun to see what men and women hams think about things! What about a checklist with an item per line, and a box for " Y " or " N " after each one?

Bob listed 28 "really don'ts" and 49 "really dos." That makes a total of 77 things to feel strongly about. I would like readers to send me their opinions on any or all of these 77 "reallys," either by mail or by packet BBS (KZ10 @ WB1DSW). The message could be kept short by just sending a

77 -character long "opinion string" of Y's (like) and N's (don't like).
I'll tabulate the answers and send the results to ham radio magazine, because, as the last line of the editorial said I also like "magazines crazy enough to publish this."
That's what the last " $Y$ " in my opinion string stands for:
YYNNNNYYNNNNNNNNNNNNNN NNNNNNYYYYYYYYYNYYYYYYY YYYYYYNYYYYYYYYYYYYYYYYY YYYYYYYY.
I'm looking forward to hearing from a lot of readers!

Dave Bushong, KZ1O
2 South Spring Street
Concord, NH 03301-2424

## a word of caution

## Dear HR:

Thank you for the article, "Solar Activity and the Earth's Magnetosphere," (August, 1987). It's very well written, and Bradley Wells is to be congratulated. For the layman, it answered many questions regarding the sun's relation to radio propagation. It also provided a good summary of the mechanics of the lines of magnetism.

There is one point I would like to bring to your attention, however. There are at least two instances where the phrase "may be visible to the naked eye" occur: on page 11, under the subhead "sunspots," and on page 13 under "flares."

At the risk of appearing overly cautious, it seemed to me that this implies that all one has to do is to gaze at the sun and these flares or sunspots would be apparent. However, readers who value their eyesight should be warned that "gazing" (my word) at the sun can be devastating. I'd therefore suggest a word of caution to the casual reader.

I hope there will be many more pieces about the sun; with the Solar year apparently coming out of its "dip," we could all benefit from a greater understanding of solar phenomena.

Rupert A. Wood, WB4ZOF
Bethesda, Maryland 20816-1760

## Matching Pair TS-711A/811A vhF/UHF all-mode base stations <br> The TS-711A 2 meter and the TS-811A <br> - Automatic mode selection.

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Optional accessories.

- IF-10A computer interface - IF-232C level translator - CD-10 call sign display - SP-430 external speaker - VS-1 voice synthesizer - TU-5 CTCSS tone unit - MB-430 mobile mount - MC-60A, MC-80, MC-85 deluxe desk top microphones
- MC-48B 16-key DTMF, MC-43S UPI

DOWN mobile hand microphones

- SW-200A/B SWR/power meters: SW-200A $\quad 1.8-150 \mathrm{MHz}$ SW-200B $\quad 140-450 \mathrm{MHz}$
- SWT-1 2-m antenna tuner
- SWT-2 70-cm antenna tuneI
- PG-2U DC power cable

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# tomorrow's receivers: what will the next 20 years bring? 

New techniques, technologies promise lower power, smaller size, higher performance

It seems that with each new issue of ham radio and other journals, we witness new technological developments affecting nearly every aspect of Amateur Radio. From time to time many of us ponder the questions, "Where is it all going?" and "What will rigs look like 10,20 , or more years from now?"
Predicting the effects of today's research on tomorrow's reality is always tricky business. But new techniques now in use in commercial and military radio systems are likely to find their way into Amateur applications sooner or later. I've discussed some of these techniques here, emphasizing what I see as their implications for Amateur Radio design.
Recent breakthroughs in technology may change some of the fundamental ground rules not only of radio engineering, but of electrical engineering in general. Consequently, two levels of development will be addressed here: first, those techniques in current use and second, those which may be possible in the near future.
Figure 1 shows a block diagram of a typical radio receiver. This is the familiar superheterodyne design, which has been predominant for nearly 60 years. Most commercial receivers on the market today use this same architecture - and in truth, there's been little improvement in radio performance for the past 30 years!'
Other characteristics have certainly changed for the better, however: size, power consumption, 12 -volt operation, frequency stability and accuracy, and ease of operation, for example. Yet the basic receiver functions remain the same; an rf signal down to the submicrovolt level must be amplified, converted, filtered,
amplified again, demodulated, amplified again, and then converted into acoustic audio. There's nothing to suggest that the principle of rf input and audio output will change as a basic function for radio engineers. Rather, it's how you get from point $A$ to point $B$ that's undergoing a quiet revolution.

Perhaps the most striking developments have been in miniaturization. There's a continuous trend towards developing components with excellent specifications but with smaller sizes and lower power consumption.

## rf amplifier

The first stage of a receiver largely determines the noise figure. Up to about 15 or 20 MHz , there's little advantage in using low-noise amplifiers because atmospheric and galactic noise are more significant than the noise figure of the typical first mixer stage. For this reason the preamp has actually disappeared from many hf receivers. Diode ring mixers typically have about a $7-\mathrm{dB}$ noise figure, which is quite adequate for most hf receivers. The preamp also lowers the dynamic range of a receiver as it increases the rf level to the first mixer. At VHF and higher, the atmospheric noise drops and the receiver noise figure becomes one of the most important system specifications. At VHF frequencies and higher, the GaAsFET has dramatically reduced receiver noise figure specifications. This trend will continue as GaAs technology improves and prices decline.

## first mixer

The most common rf mixer is the passive quad diode ring. It has a relatively low noise figure and the limitation to dynamic range is mainly a function of LO power used. A generalization can be made about the LO power necessary to handle a given rf power level: the ratio of maximum rf input power to minimum LO power is about $1: 10$. That is, for a diode mixer to handle 100 mW of rf , the LO power must be at least 1 watt.

By Robert J. Zavrel, Jr., W7SX, P.O. Box 23447, Tucson, Arizona 85734

fig. 1. Typical present-day superheterodyne receiver.

fig. 2. Gilbert Cell multiplier-mixer.

There have been two major developments in mixer technology during the past few years. The first is the passive FET ring, exemplified by the Siliconix Si8901. With this device, gate voltage rather than a forwardbiasing current turns the switches "on" and "off." Since the gates represent high impedances, voltage/ power ratios can be increased, thus lowering the LO power requirements dramatically. Indeed, to handle the same $100-\mathrm{mW}$ rf power in our diode ring example, the Si8901 requires about 25 mW of $L O$ power instead of the 1 watt mandated by the diode rings. The other critical specification is the third-order intercept point, which is necessary for defining the useful dynamic range. Again, the Si8901 greatly surpasses the old diode ring mixer. ${ }^{2}$

Working from the same empirical thinking that led to the development of the Si8901, a passive GaAsFET ring should surpass the performance of the silicon Si8901 by perhaps a 7-dB increase in third-order in-
tercept point specification. Since the GaAs devices would be used as switching elements rather than active amplifiers, the $1 / f$ noise limits of these devices wouldn't be an issue. They could be used at sub-audio frequencies with comparable noise performance at hf.

Although purported as a passive mixer, the Si8901 should also make an excellent active mixer. Using the same concepts as the old U350, the DMOS Si8901 should outperform its JFET cousin. The smaller geometry SD201 DMOS family made excellent VHF lownoise amplifiers before Signetics discontinued its DMOS line several years ago. Siliconix and the other DMOS manufacturers have chosen not to build these smaller devices, although both mixer and amplifier performance could be enhanced by such a modification.

As the world of digital integrated circuits has shifted its attention to faster CMOS technologies, advances in analog bipolar IC techniques have quietly proceeded. A fundamental bipolar mixer circuit is the


| LAT | $23.7^{\circ} \mathrm{s}$ | ECHO | 86 ms | ELEU | $-2.1^{\circ}$ |
| :--- | ---: | :--- | ---: | :--- | :---: |
| LON | $95.3^{\circ} \mathrm{w}$ | FRQ | 145.8076 | AZIM | $153.7^{\circ}$ |
| HGT | 7782 km | DOP | -1359 Hz | OREIT | 3403 |
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| BANDWIDTH | 420-460 MHz |
| GAIN | . 8.8 .9 dBd |
| vSWR | ..........1.5:1 |
| F/B | 20 dB |
| BEAMWIDTH | $60^{\circ}$ |
| FEED IMP. | 50 ohm |
| BALUN | 4:1 coax |
| MECHANICAL: |  |
| ELEMENT LENGTH | ... $1311 / 2^{\prime \prime}$ max. |
| BOOM LENGTH | -.......28" |
| TURN RADIUS. | $28^{\prime \prime}$ |
| WINDLOAD | 2 sq. ft. |
| WEIGHT | 1 lb . |
| MAST | $11 / 2^{\prime \prime}$ o.d. |
| MOUNT | ar |


| 440-10X |
| :--- |
| ELECTRICAL: |
| BANDWIDTH. |
| GAIN |
| VSWR |
| FIB. |
| BEAMWIDTH. |
| FEED IMP |
| BALUN |
| MECHANICAL: |
| ELEMENT LENGTH |
| BOOM LENGTH |
| TURN RADIUS |
| WINDLOAD |
| WEIGHT |
| MAST |
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MECHANICAL:
HEIGHT.............................................................. $6^{\prime \prime}$

WEIGHT ............................................ $21 / 2$ lbs.
MAST .................................................... 11/2" o.d.
CJ220
ELECTRICAL
BANDWIDTH. ........................220-224 MHz
GAIN .................................................... 1.8 dBd

VSWR ....................................................... 1.5:1
FEED IMP........................................... 50 ohms
NO GROUND PLANE REQUIRED
MECHANICAL:
HEIGHT ............................................................ 40"
WEIGHT .................................................. 2 lbs.
MAST ................................................. $11 / 2^{\prime \prime}$ o.d.
CJ440
ELECTRICAL:

| BANDWIDTH. | 420-470 MHz |
| :---: | :---: |
| GAIN | 1.8 dBd |
| VSWR | 1.5:1 |
| EEED IMP | 0 ohm |

NO GROUND PLANE REQUIRED
MECHANICAL
HEIGHT
191/4"

- 109
.1 lb .
MAST $11 / 2^{\prime \prime}$ o.d

Gilbert Cell (fig. 2). Though the most familiar Gilbert Cell ICs are the Motorola MC1496 and MC1596, there are many manufacturers of these devices today. Over the past few years there have been several variations on this original commercial design. Good noise performance has been achieved with the Signetics NE602, but it can't handle the higher input levels necessary for good hf first mixer design. The NE602, however, is perhaps the finest mixer available among low power consumption mixers. Advances in bipolar processing are pushing noise figures down and power handling capabilities up in simulation models as well as in newly available devices. If this trend continues, the diode ring may become an endangered species.

## local oscillator

Perhaps the most dramatic advances in receiver technology have been in the design of local oscillator circuitry. Very exotic mechanical assemblies evolved for LO tuning in the 1950s. (Remember the NC300, HOs, and Collins receivers?) Permeability tuned oscillators (PTOs) simplified things in the 1960 s with the SB300, R4, and S-lines. Today, PTO LO performance remains difficult, if not impossible to duplicate with PLL synthesis, given the constraints of typical Amateur budgets. Synthesizers offer distinct advantages in that they can be directly controlled by microprocessors and don't require special mechanical rigidity or moving parts. A single crystal oscillator frequency is divided down to some low value and then "phaselocked" up to the desired LO frequency. At the output of the VCO, a multiple of the reference frequency equal to the reference frequency times the divider's " N " value appears (see fig. 3 ). This represents a simple phase-locked loop synthesizer, but it contains all the necessary building blocks of a more sophisticated system. If the reference is 1 kHz and the divider is set to $\mathrm{N}=7005$, the VCO output will be $7005 \times 1 \mathrm{kHz}$, or 7.005 MHz . Discrete frequency steps of 1 kHz will be possible because only division by whole numbers is possible in this system. N determines the output frequency because the dc control voltage feedback will "lock" the VCO to the output frequency that provides equal frequency inputs to the phase detector.
Another type of synthesizer - the "direct digital synthesizer" or DDS - holds great promise. To understand how DDS works, two concepts must be understood: first, the concept of how digital-to-analog converters function and second, the Nyquist Theorem. I'll discuss each of these very briefly.

A digital-to-analog converter (DAC) takes a binary number and "converts" it into a discrete voltage or current value. An eight-bit DAC, for example, can have a maximum of 256 different voltage outputs. The digital eight-bit "word" can be generated by a micro-

fig. 3. Simple digital PLL frequency synthesizer.

fig. 4. Sine wave digital approximation.
processor or memory circuit. A sine wave or any other waveform can be approximated by discrete steps as shown in fig. 4. For LO applications, sine wave approximation is preferred because sine waves have the lowest harmonic content. (A perfect sine wave will have no harmonic content.)

The Nyquist Theorem states that a sine wave can be derived if at least two discrete amplitude samples per period are obtained. Thus, if we want to synthesize a $5-\mathrm{MHz}$ sine wave with a DDS, we'll need an updating clock rate of at least 10 MHz . With DDS, a constant sample rate can be used to synthesize any frequency up to half the sample rate with excellent frequency resolution ( 0.1 Hz typical). Figure 5 shows how 1 - and $2-\mathrm{MHz}$ sine waves can be generated by a $10-\mathrm{MHz}$ clock and a DAC. The microprocessor computes the values to be sequenced by the DAC for a given frequency output and a given clock rate. This special processing function is called a phase accumulator. Higher clock rates allow for more samples per period. More samples, in turn, allow for better approximation of the sine wave shape. Also, the greater number of bits allows for more discrete amplitude steps, which also enhance the accuracy of the sine wave approximation. DAC integral linearity affects waveform accuracy and harmonic levels. Indeed, the major efforts in DAC development are directed towards

fig. 5. DDS sinewave synthesizer. Any frequency can be synthesized up to $1 / 2$ the sample rate by changing the digital numerical value at each sample point.
better resolution (i.e., more bits) at higher update speeds. Off-the-shelf video-speed DACs now allow excellent performance for DDS circuits well into the hf spectrum. The Burr-Brown DAC63 is such a device. As DACs become faster and more accurate, the phase noise and harmonic performance improve.

Compared with PLL synthesizers, DDS offers other advantages. Since all the parameters of the waveform (frequency, amplitude, and phase) are digitally controlled, frequency hopping, or QSY, is almost instantaneous. PLL systems, on the other hand, have some finite settling time. In addition, nearly any type of modulation is possible if the applicable parameter is changed in accordance with a modulating wave-
form. Outstanding linearity is possible even at very wide bandwidths - in fm, for example. ${ }^{3}$ To achieve the necessary low spectral noise densities demanded by hf LOs, more work is needed; however DDS holds great promise as a replacement for PLL synthesizers.

Figure 6 shows a direct conversion phasing SSB receiver. Traditional analog phase and amplitude nulling techniques employing all-pass active filters could yield $40-\mathrm{dB}$ image rejection at best. The problem of this nulling is compounded by the need for broadband 90 -degree phase shifters. ${ }^{4}$ However, if we digitize the two signals the phase and amplitude nulling can be performed using a digital signal processor (DSP). Small errors in phase and amplitude can be removed

fig. 6. Direct conversion SSB receiver.

fig. 7. Digitized radio of tomorrow.
and the ultimate image rejection will correspond to the bit resolution of the analog-to-digital converter ADC. A 16 -bit ADC, for example, could provide $96-\mathrm{dB}$ image rejection using an ideal DSP. This would make an excellent receiver. Very sharp analog audio filters would be required before the ADCs. Philips has produced such a dual-channel filter in monolithic form, but it's not yet commercially available. More traditional upconversion schemes using DSP are discussed in an outstanding new textbook. ${ }^{5}$

Once the demodulated audio baseband signal is digitized, digital filtering techniques can be used. Very steep skirt notch and bandpass filters can be arranged. The amplitude coefficients can be manipulated to allow idealized audio AGC. Alternately, an AGC voltage can be provided through a DAC which controls an rf stage gain. Finally, the digitized audio can be converted back into analog form via a DAC, in much the same way as compact disc players function. The BurrBrown PCM54 is an excellent 16-bit DAC for this application.

Figure 7 represents a daydream of where radio engineering state of the art might be within 20 or 30 years. A bandpass filter from 0.5 to 30 MHz tunes the entire hf spectrum. A futuristic 16 -bit ADC with a $75-\mathrm{MHz}$ sampling rate provides a $96-\mathrm{dB}$ dynamic range over the bandwidth. The entire spectrum is digitized. All filtering, demodulation, AGC, and such, is performed in the rather sophisticated DSP. A PCM54 is then used to output the audio to an audio amplifier.

## superconductors

In April the news media reported that a group working at an IBM facility in Switzerland had developed a new material that remains a superconductor up to 85 degrees K. This material, by itself, makes superconductors possible at liquid nitrogen temperatures, thus dramatically lowering the costs of using this class of material. Perhaps of far greater importance is that this work represents a crucial breakthrough for creat-
ing better superconducting materials. There is even talk of superconductors at room temperatures. What can this mean?

Superconductors are created when a material is cooled down to a critical temperature. Below the critical temperature the material exhibits zero electrical resistance. When superconductor offers literally no resistance at room temperature, electronic device technology could advance dramatically. Josephson junction or SQUID digital circuits could render even the fastest computers now available obsolete. For analog and rf circuits, zero resistance could have great implications for speed and noise specifications. Thermal noise disappears in superconductors as $V^{2}=4 K T R B$. Never mind Boltzman; $R$ is now zero. With zero resistance, charge mobility - a limiting factor for the speed of any semiconductor material - becomes quite high.

With superconductors, storage "battery" technology would be revolutionized. Imagine an electromagnetic car battery the size and weight of a donut! Charging efficiency would approach 100 percent.

Superconducting antennas and transmission lines would improve efficiency and lower system noise figures. Can you imagine 160 -meter loading coils with zero resistence?

This is the most exciting development in solid-state physics since the invention of the transistor. The implications may by far outweigh the transistor's effects on the world. Electronic and electrical power engineers will have to rewrite all the books - again.

## what to watch for

The radio art is in constant evolution. Here are some of the trends to watch for between now and the advent of the twenty-first century:

- Continued miniaturization of all components, thanks to higher levels of circuit integration and advances in wafer processing techniques.
- Lower supply voltage and current requirements for


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- Dick Tracy's two-way wrist radio will become a reality by 1995.

Putting predictions into print preserves the prophet's prognostications for posterity. It might be amusing, in the year 2007, to dust off your yellowed, musty copy of this issue to see just how far off the mark we were. Happy dreams!

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# designing a state-of-the-art receiver 

## Readily understood - though not greatly utilized - concepts mean better performance

The state of the art in hf receiver design using semiconductors has improved greatly. The use of either CATV-type transistors and double-balanced mixers using hot carrier diodes or double-balanced mixers with switch-type FETs has eased the large-signal handling problem of just a decade ago.
One weak link in the chain, however, remains; this is the synthesizer, with its inherent noise contributions. To a large extent the overall architecture of the receiver and the synthesizer determines its performance, and even the best high-performance components - placed in the wrong sequence - can cause a good design to fail.

## systems approach

Because military and commercial users depend on high performance receivers for surveillance and/or point-to-point communication, it's inevitable that these same technological advances will filter down to the Amateur community. In fact, in a cursory examination, the spec sheets of both commercial and Amateur communications receivers look quite similar.
Besides providing the "essentials," modern communication receivers offer additional features, sometimes re-
ferred to as "bells and whistles"; these features include improved user interfaces or computer interfaces for remote control. Since the commercial and Amateur markets are price-sensitive and also very sensitive to proof of performance, any claims of lower capabilities are noticed. Consequently, when on-the-air tests of some latemodel receivers suggested poorer performance than previous models, this raised the question of why, despite the knowledge acquired in recent years, such an inconsistency should occur.

Figure 1 is a functional block diagram of a modern microprocessor-controlled communication receiver. This diagram is representative of most modern design approaches and can be used to evaluate possible advantages and weaknesses, and to point out areas of potential difficulty.

## operation

The rf signal is introduced into the receiver in one of two ways:

- at the input of a $30-\mathrm{MHz}$ low-pass filter via a variable attenuator, which is controlled by an overload detection circuit activated at the first and second i-f level;
- or for receiving frequencies below 400 kHz , via a variable attenuator and low-pass filter combination.
The first mixer, which is responsible for the third-order intercept point, is driven by an extremely pure synthesized local oscillator. To terminate the double-balanced mixer properly, a diplexer (high-pass/low-pass filter) is used to absorb energy outside the crystal filter passband. The input impedance of the crystal filter rises significantly outside the passband of the crystal filter.

By Ulrich L. Rohde, KA2WEU/DJ2LR, 52 Hillcrest Drive, Upper Saddle River, New Jersey 07458


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- Place a KPA5 in a dicast box with a VOR (video operated relay) to make a hill top video repeater. Repeat other ATVers, weather radar or Space Shuttle video.

WHAT IS REQUIRED FOR A COMPLETE OPERATING SYSTEM? Either a TVC-2G or TVC-4G downconverter connected to any TV set tuned to channel 3 , and coax cable to a good 70 cm antenna to receive. Connect up the TX70-1 or package up the KPA5, add 12 to 14 vdc , antenna, and any home TV camera, VCR, or computer with composite video output. It's that easy!

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While most commercial or military high-performance receivers employ the input stage combination, most Amateur equipment uses a double-balanced mixer that incorporates adjustable-gain JFETs. As a result of its sensitivity to output impedance changes, the mixer suffers reduction in large-signal performance. The recent trend in mixer design involves the use of termina-tion-insensitive mixers whose cleverly designed bridge circuits ignore the effects of reactive terminations. Passive mixers use hot carrier diodes; switching-type mixers use FETS - for example, a pair of matched SD 100 transistors - and achieve intercept points between +35 and +45 dBm .
Following a six- to eight-pole crystal filter is an amplifier stage which has medium gain and high dynamic range. This is typically achieved through the use of rf feedback. In addition, it is worthwhile to incorporate an AGC circuit between this amplifier and the mixer.

The signal, which is now in the 75 - to $100-\mathrm{MHz}$ frequency range, is converted to a lowi-f frequency - for example, from 200 kHz to 2 MHz - by the second mixer. The second mixer must also have high dynamic range, but it can be a passive double-balanced mixer. (The latest advances in receiver design have included the use of careful filtering of the local oscillator synthesizer outputs, thereby reducing spurious responses. ) The amplifier that follows this mixer compensates for the sec-ondi-f mixer losses. This, in turn, is followed by a popular frequency range crystal filter that is readily available from a number of manufacturers.

## gain distribution is important

Each of these stages has very little gain - typically less than 12 dB . The main amplification of the signal takes place in thei-fsections. (This is different from what happens in Amateur receiver designs.) The problem with designing most of the gain into the i-f stages has to do with the ability to build the i-f amplifier circuits stable and free of unwanted oscillations. To minimize in-band intermodulation distortion, differential-type amplifiers with AGC stages are used. In many cases this requires a great deal of shielding and careful selection of grounds, since up to $100-\mathrm{dB}$ open loop gain in the i-f section may be required.

One sign of good receiver design is evident when the noise of the first mixer, with no antenna connected, already shows slight AGC action, which can be monitored on the S -meter of the receiver. If signals of $1-\mu \mathrm{V}$ or better are required before any S -meter action occurs, then the above design guidelines have not been followed.

Although I've noted these things thoroughly and repeatedly in previous articles, very few companies have followed through with this concept because it's much less expensive to move the gain towards the antenna than to build high-gain i-f stages.



fig. 4. Architecture of the internal computer system found in a modern fully synthesized receiver.

Interestingly enough, the NRD 525 receiver, which follows these recommendations but is still fairly inexpensive, is one of the better designs. Figure 2 shows a typical block diagram with the various noise, gain and intermodulation distortion products specified. Such an analysis must be carried out and should be published together with the receiver specifications.

In fig. 1, the internal bus for the receiver that controls a variety of functions transfers digital data streams that consist of short-duration pulses with fast rise times. Consequently, significant shielding is required in this section in order to isolate the digital circuits and their concommitant switching spikes from the analog portion of the receiver. Many modern receivers suffer from this effect, in which background switching noise masks lower level signals. To make things worse, the synthesizer can also pick up some of the switching signals.

## synthesizer design

Modern receivers should incorporate fully synthesized
local oscillators and provide between 1-and 10-Hz resolution. All of the auxiliary frequencies in the design must be derived from the master (oscillator) standard.

The frequency synthesizer in this example uses two main loops in its multi-loop design. VCO1, which oscillates between 127 MHz and 139 MHz , is phase locked in steps of 1.2 kHz ; its output is then divided by 120 to an output frequency of approximately 1 MHz , which is then mixed with the $79.2-\mathrm{MHz}$ standard. The difference frequency components are introduced into a $78.1-\mathrm{MHz}$ crystal filter which removes all unwanted signals. The other portions of the synthesizer provide auxiliary frequencies. The areas where the phase detectors are located are heavily shielded; fairly high frequencies for the reference detectors are used for best noise performance.

Figure 3 shows a synthesizer that utilizes this design approach. In this design, analog and digital circuits are carefully separated. The sections of the synthesizer most vulnerable to picking up extraneous signals are the lines going into the output VCO (VCO2).

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Depending on the type of phase detector used, the lines that feed the tuning diodes can be either very high impedance or low impedance. Inexpensive solutions frequently lead to such high-impedance feeding points, which then become "antennas" collecting all the switching noise. The use of circuits incorporating microwave transistors allows the design of discrete low-impedance amplifiers for this purpose. If the driving point impedances for the tuning diodes can be held at 100 ohms as opposed to the 100-k line impedance typically found, the sensitivity for pickup of stray signals is reduced by a factor of 100,000.

Another reason for noisy synthesizers is the use, in the synthesizer loops, of operational amplifiers that are too noisy. Wherever possible, either discrete low-noise amplifiers or Darlington stages must be used.

## use of microprocessors

Today's microprocessor-controlled receivers feature built-in clocks, frequency scanning with variable scan rates, availability of at least 100 channels and channel scanning, plus a combination of receiver control functions such as the serial RS-232 or IEEE-488 bus remote control capabilities. Because the BFO and the main oscillator are both synthesized, the combination of the two allows either passband tuning or variable bandwidth.

Another area of interest in the use of microprocessors is the linearization of the transfer characteristic of the tuning range of the oscillator and the linearization of the S-meter. The microprocessor can also switch the tuning rates to correspond to the operating mode and select the appropriate bandwidth receiving crystal filters required for that same mode. Digital implementation of signal analysis allows demodulation of RTTY and Morse code. Many other novel approaches are possible.

Figure 4 shows the architecture of such an internal computer system. One of the frequent mistakes made in this context is the use of only one microprocessor, which gets overloaded, or the use of four-bit microprocessors. In better radios, eight-bit microprocessors, which can handle all these functions efficiently, are used. The best approach is parallel processing.

## summary

By following these simple guidelines and using architecture similar to that illustrated in figs. 1 and $\mathbf{2}$, it is possible to build receivers that come close to the limits of physics, yet still remain cost- effective.

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# a CAT control system for the Yaesu FT-757GX 

## C-64 BASIC routine tunes popular transceiver

An earlier article on the CAT system, based on the Tandy TRS-80 Model 100, attracted the attention of a considerable number of users of Commodore $64{ }^{\text {® }}$ microcomputers. ${ }^{1,2}$ But while it was a relatively simple task to convert the TRS-80 program for other micros with a standard RS-232C port, it wasn't as easy to convert the program for the popular $\mathrm{C}-64$.

Converting the unique Commodore "inverted TTL level" format is no problem because the CAT system also works with TTL levels. But the standard baud rates of the $\mathrm{C}-64$ stop at 2400 , and CAT works at 4800 baud. (In this case, baud and bps give the same number, so we'll stick to "baud," since that's what's used in the Commodore and Yaesu literature.)

It's possible to obtain the proper parameters for 4800 baud using a two-step formula for calculating "userspecified baud rates. ${ }^{\prime 2}$ Checking the output with an oscilloscope looked promising, but in practice the data transfer wasn't reliable, and bytes sometimes were lost on their way from BASIC to the radio. Commodore specialists have several explanations for this. Some say that it depends on the physical layout of the printed circuit board; others contend that Commodore BASIC has problems handling the NUL character. Whatever the reason, the data didn't always reach the RS-232C output buffer in good order.
In this program these problems are avoided by replacing the BASIC RS-232C statements with routines written in machine language. The parameters are POKEd into temporary storage in memory locations 52592 to 52596. The command byte (see table 1) goes into location 52592. The frequency number is sliced into four bytes (i.e., $12,345.67 \mathrm{kHz}$ converts to $01,23,45$ and 67 ), which are stored in the next four locations.

Another problem has also been solved in machine lan-
guage. The frequency bytes just mentioned are in the CAT Binary Coded Decimal format, and ideally would be passed as such to the RS-232C port. But the Commodore BASIC interpreter expects all numbers to be in decimal form and converts them into hexadecimal when the program is executed. A look-up table is used to reconvert the hex into the proper $B C D$ format. The five bytes are then sent out one by one, starting from the highest address, as required by the CAT system.

## BASIC program

The BASIC part of the program (fig. 1 ) is straightforward and can be segmented as follows:

The program is initialized in lines $\mathbf{1 0 0}$ to $\mathbf{2 2 0}$. A title screen at lines 3000 to 3160 (subroutine) is displayed while the machine language part in lines 4000 to 4114 (subroutine) is being loaded. SYS 52480 is similar to OPEN File No. 1 for 4800 baud, eight bits per byte, two stop bits, and no parity. Line 210 determines the starting frequency.

The main screen is set up in lines $\mathbf{1 0 0 0}$ to $\mathbf{1 1 5 0}$ (see fig. 2). The keys available for commands are indicated within brackets. The upper row on the keyboard is used for general commands; the lower row - plus " $A$ " and " $;$ " - for tuning in steps of 10 Hz to 100 kHz . " $F$ " is for steps of any size and " O " for quitting the program.

Note that Band Down and Band Up have different functions, depending on whether the FT-757GX is in Amateur Band or General Coverage mode, and whether or not MR/VFO has been activated (see the FT-757GX Operating Manual). This short program doesn't take into account frequency changes made with Band Down or Band Up, so in order to get the correct screen display, you'll need to reinitialize the program by pressing " $F$ " and entering the actual frequency before using the Fine Tuning keys. This isn't a problem, since you can still go directly to any frequency with the " F " command.

By Kjell W.Strom, SM6CPI, P.O. Box 2, I-28041
Arona, Italy

Table 1. Command byte codes.

| function | hexadecimal | decimal |
| :--- | :---: | :---: |
| Band Down (multifunction) | 08 | 8 |
| Band Up (multifunction) | 07 | 7 |
| Dial Lock (on/off) | 04 | 4 |
| Clarifier (on/off) | 09 | 9 |
| Split Frequency (on/off) | 01 | 1 |
| Switch between VFO A and B | 05 | 5 |
| Transfer VFO to Memory | 03 | 3 |
| Transfer Memory to VFO | 06 | 6 |
| Exchange between VFO and |  |  |
| $\quad$ Memory | OB | 11 |
| Temporary check of Memory | O2 | 2 |
| Frequency Set | OA | 11 |

fig. 1. BASIC language program for CAT control of Yaesu FT-757GX.

10 REM

30 REM
CONTROL FOR VAESU FT-757GX
AND COMMODORE 64
BY KJELL W. STROM, SM6CP
50 REM JUNE 5, 1987
60 REM
70 REM
100 REM *** LOAD ML AND OPEN FILE FOR 4800 BAUD ***
110 GOSUB 3000:GOSUB 4000:SYS 52480
200 REM *** SET (NITIAL FREQ ( 10000 KHZ ) ***
$210 \mathrm{~A}=10000$
220 GOSUB 2100
1000 REM *** MAIN SCREEN ***
1010 PRINTCHR\$(147)"[RVS] YAESU FT-757GX CAT PROGRAM BY SM6CPI "
1015 PRINT:PRINT:PRINT
1020 PRJNT"NEW FREQUENCY [F]
QUIT [Q]"
1030 PRINT:PRINT:PRINT:PRINT"
FINE TUNING"
1040 PRINT"
$\langle<-\langle K H Z\rangle+\rangle>"$
1050 PRINT"[A]100
100[;]"
1060 PRINT
1070 PRINT"10 $5 \quad 1 \quad .1 \quad .01 .01 \quad 1 \quad 1 \quad 5 \quad 10^{\prime \prime}$
1080 PRINT"[2] [X] [C] [V] [B] [N] [M] [,] [.] [/]"
1090 PRINT"[DOWN]
$\begin{array}{lll}1100 \text { PRINT" [1] BAND DOWN } & \text { [2] BAND UP" } \\ \text { 1110 PRINT" }\end{array}$
$\begin{array}{lll}1110 \text { PRINT" } & \text { [3] DIAL LOCK } & \text { [4] CLARIFIER" } \\ 1120 \text { PRINT" } & \text { [5] SPLIT FQ } & \text { [6] VFO A/B" }\end{array}$
1130 PRINT" [7] $V=>M \quad$ [8] $M=>V^{\prime \prime}$
1140 PRINT" [9] $V=>/<=M \quad$ [0] MR/VFO"
1150 PRINT "[HOME][DOWN][OOWN]
1160 GET C $\$: I F$ C $\$=" "$ GOTO 1160
1170 IF C $\$=$ " $B$ " THEN $A=A-.01:$ G0T0 1600
1180 [F C $\$=" N^{\prime \prime}$ THEN $A=A+.01:$ G0T0 1600
1190 IF $C \$=" V "$ THEN $A=A-.1: G O T 01600$
1200 IF $C \$=" M "$ THEN $A=A+.1: G 0101600$
1210 IF $C \$=" C "$ THEN $A=A-1$ :GOTO 1600
1220 [F $C \$="$ ", THEN $A=A+1$ : GOTO 1600
1230 IF C $\$=$ " $X$ " THEN $A=A-5:$ GOTO 1600
1240 IF C $\$={ }^{\prime \prime}$." THEN $A=A+5: G 0 T 01600$
1250 IF $C \$=" Z "$ THEN $A=A-10:$ GOTO 1600
1260 IF $C \$=" / "$ THEN $A=A+10$ :G010 1600
1270 IF C $\$=$ "A" IHEN $A=A-100: G 0 T 01600$
1280 IF $C \$=" ; "$ THEN $A=A+100: G 0 T 01600$
1290 If C $\$=" F "$ THEN GOSUB 2800:GOTO 1000
1300 IF C $\$="$ !" THEN POKE 52592,8:SYS 52526:GOTO 1160
1310 IF C $\$=" 2 "$ THEN POKE 52592,7:SYS 52526:GOTO 1160 1320 If C $\$=$ "3" THEN POKE 52592,4:SYS 52526:GOTO 1160 1330 If $C \$=" 4 "$ THEN POKE 52592,9:SYS 52526:GOTO 1160 1340 IF C $\$=$ "5" THEN POKE 52592, 1:SYS 52526:GOTO 1160 1350 IF C $\$={ }^{\prime \prime} 6$ " THEN POKE 52592,5:SYS 52526:GOTO 1160 1360 If $\subset \$=" 7$ " THEN POKE 52592,3:SYS 52526:60T0 1160 1370 IF C $\$=" 8$ " THEN POKE 52592,6:SYS 52526:GOT0 1160 1380 IF C $\$=" 9 "$ THEN POKE 52592, 11:SYS 52526; GOTO 1160

1390 IF $C \$=$ ""0" THEN POKE 52592,2:SYS 52526:6010 1160 1580 If $\mathrm{C} \$=" \mathrm{Q}$ " GOTO 2900
1590 GOTO 1160
1500 REM *** ROUND OFF AND CHECK RANGE ***
$1610 \mathrm{~A}=\mathrm{INT}(\mathrm{A} * 100+.5) * .01$
1620 IF $A<500$ THEN $A=500$
1630 JF A 29999.99 IHEN $A=29999.99$
1640 GOSUB 2100
1650 GOTO 1150
2100 REM *** SLICE FREQ AND OUTPUT ***
2110 A\$ $=\operatorname{MIDS}(S T R \$(A), 2)$
$2120 \mathrm{IF} \mathrm{A} A \operatorname{INT}(A)$ THEN $A \$=A \$+{ }^{\prime \prime}{ }^{\prime \prime}$
$2130 \mathrm{~A} \$=" 000 "+A \$+000$
2140 FOR I=1 TO LEN(AS)
2150 DP $\$=\mathrm{MID} \$(A \$, 1,1)$
2160 IF DPS $=$ "." THEN DP $=1: G 0102400$
2170 NEXT
$2400 \mathrm{~A} \$=\mathrm{MID} \$(\mathrm{~A} \$, \mathrm{DP}-6,6)+\mathrm{MID} \$(A \$, \mathrm{OP}+1,2)$
$2410 \mathrm{~F} 1=\mathrm{VAL}(\operatorname{MID} \$(A \$, 1,2))$
2420 F2 $=\mathrm{VAL}(\operatorname{MID} \$(A \$, 3,2)$ )
2430 F3 $=\operatorname{VAL}(\operatorname{MIO} \$(A \$, 5,2))$
2440 F4 $=$ VAL (MID $\$(A \$, 7,2)$ )
2450 POKE 52593,FI
2460 POKE 52594,F2
2470 POKE 52595,F3
2480 POKE 52596,F4
2490 POKE 52592,10
2500 SYS 52512
2510 RETURN
2800 REM *** NEW FREQUENCY ***
2810 INPUT"[DOWN][DOWN][DOWN]FREQUENCY KHZ";A
$2820 \quad A=\operatorname{INT}\left(A^{*} 100+.5\right) * .01$
2830 IF $A<500$ THEN $A=500$
2840 IF $\mathrm{A}>29999.99$ THEN $\mathrm{A}=29999.99$
2850 GOSUB 2100
2860 RETURN
2900 REM *** REM CLOSE FILE AND QUIT ***
2905 PRINT:PRINT:PRINT
2910 PRINT" ARE YOU SURE?"
2920 GET C\$:IF C $\$={ }^{* \prime *}$ G010 2920
2930 IF C $\$=" Y$ " THEN SYS 52578:PRINT CHR (147):END
2940 GOTO 1000
3000 REM *** TITLE SCREEN WHILE ML IS LOADING ***
3010 H1\$=" CAT PROGRAM FOR'
3020 H2 $\$=" \quad$ YAESUFT-757GX"
$3030 \mathrm{H} 3 \$=" \quad$ BY KJELL W. STROM, SM6CPI"
3040 PRINTCHR\$(147):PRINT:PRINT:PRINT:PRINT
3050 FOR I=1 TO LEN(H1 $\$$ )
3060 PRINT MID\$(H1\$,I,1);
3070 NEXT
3080 PRINT:PRINT
3090 FOR I $=1$ TO LEN(H2\$)
3100 PRINT MID\$(H2\$,1,1);
3110 NEXT
3120 PRINT:PRINT:PRINT
3130 FOR I $=1$ TO LEN(H3\$)
3140 PRINT MID\$(H3\$,I,1);
3150 NEXT
3160 RETURN
4000 REM *** LOAD ML. ROUTINES ***
4010 FOR I $=52480$ TO 52696:READX:POKEI,X:NEXT
4020 RETURN
4100 DATA $169,1,162,2,160,3,32,186,255,169,4,162,104,160,205$
4101 DATA $32,189,255,32,192,255,162,3,189,108,205,149,247,202$
4102 DATA $16,248,96,162,3,188,113,205,185,117,205,157,113,205$
4103 DATA $202,16,244,162,1,32,201,255,173,14,220,41,254,141$
4104 DATA $14,220,162,4,189,112,205,168,173,161,2,41,1,208,249$
4105 DATA $152,32,210,255,202,16,238,173,161,2,41,1,208,249$
4106 DATA $32,204,255,173,14,220,9,1,141,14,220,96,169,1,32$
4107 DATA $195,255,96,0,0,2,0,0,206,0,207,75,87,83,56,55,0,1,2$
4108 DATA $3,4,5,6,7,8,9,16,17,18,19,20,21,22,23,24,25,32,33$
4109 DATA $34,35,36,37,38,39,40,41,48,49,50,51,52,53,54,55,56$
4110 DATA $57,64,65,66,67,68,69,70,71,72,73,80,81,82,83,84,85$
4111 DATA $86,87,88,89,96,97.98,99,100,101,102,103,104,105,112$
4112 DATA $113,114,115,116,117,118,119,120,121,128,129,130,131$
4113 DATA $132,133,134,135,136,137,144,145,146,147,148,149,150$
4114 DATA 151,152,153
10000 REM *** 'RUN 10000 ' FIRST TO CHECK ML DATA LINES ***
$10010 \mathrm{~S}=0$ :FORI $=52480$ TO52696: READX: $\mathrm{S}=\mathrm{S}+\mathrm{X}:$ NEXT
10020 IF S<>22360 THEN PRINT"CHECK ML DATA!": END
10030 PRINT"ML DATA OK!"
READY.

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| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
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fig. 2. Screen display.

Commands entered from the keyboard are decoded by lines 1160 to 1590 . SYS 52526 sends the bytes to the radio without converting from hex to $B C D$, since this isn't required for the single-byte commands.

Verification that the frequency is inside the range of the FT-757GX is accomplished with lines 1600 to 1650.
In lines 2100 to 2510 the frequency parameter is sliced into four bytes, as described above, after having been converted into a string and having found the position of the decimal point. SYS 52512 is the call for sending out the frequency byte after a hex-to-BCD conversion.

The frequency input subroutine used with the " F " command is contained in lines 2800 to 2860.
The subroutine for the QUIT command is in lines 2900 to 2940.
The last part of the program contains subroutines for the title screen and for loading of the machine language part, as mentioned before.

The numbering of the program lines may seem haphazard; this is because some numbers were intentionally omitted in order to reduce the time needed for some of the GOSUBs and GOTOs. Renumbering to a tighter sequence may slow down the program a little.

After typing in the program, SAVE it and type RUN 10000 /RETURN/ to confirm that the DATA lines have been entered correctly. Otherwise, if there's a mistake in the DATA and you try a RUN, you may lose the program!

## interface

An interface circuit serves two purposes: it translates the input level to a suitable output level and stops poten-

tially harmful interference from one connected unit from reaching the other, and vice versa.

Both the C-64 and the FT-757GX CAT system work with the same TTL levels, but the current needed to pull the CAT SI line to low, through a 680 -ohm resistor, is probably higher than can be considered safe for the delicate $\mathrm{C}-64$ CIA chip. We also want to minimize the possibility of computer noise reaching the receiver and of transmitter of reaching the computer.

The Yaesu FIF-232C interface does this job. It accepts the inverted TTL level format from the C - 64 if the internal switch $\mathbf{S 0 1}$ is set to the position opposite from nor-

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mal. Since it also works with standard RS-232C format and with the two-way CAT systems of the FT-980, FT-757GXII, and FT-767GX, it can be regarded as a very flexible solution, especially since it has its own built-in power supply.
For our purpose we can also use the simple interface circuit shown in fig. 3. It receives 5 volts from the $\mathrm{C}-64$ and can be assembled on a small IC-spacing perforated board as close as possible to the 24 -position user port card edge connector. The cable from the TIL111 optocoupler output side should be shielded, with the screen connected to ground at the transceiver side only, not to computer ground. Connect all unused input pins on the 7404 IC to ground, together with pin 7.

## summary

This article has been intended to show how easily you can interface and use the CAT system with the Commodore 64 and the Commodore 128 in C- 64 mode. It also offers four machine language routines you can use in much more powerful programs, thereby adding your own special features to one of today's most appreciated transceivers.

## references

1. K. W. Strom, SM6CPI, "A CAT Control System," OST. October, 1985, page 38
2. K. W. Strom, SM6CPI, "Feedback", OST. April. 1986, page 41

## ham radio



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## a thumbwheel frequency selector for the Yaesu FT-757GX

If you happen to own a Yaesu FT-757GX transceiver, this one-evening project will make its operation more convenient and enjoyable. If you don't own one, you may find that this article will show the ease and simplicity with which features of modern computer-controllable radios can be accessed.

Because the 757's minimum incremental tuning is in $500-\mathrm{kHz}$ steps and the tuning dial moves only 10 kHz per rotation, any frequency change in other than $500-\mathrm{kHz}$ steps takes several presses of the button and an average of 12-1/2 knob rotations! This project allows thumbwheel entry of any frequency, in or out of the current band. The design makes no modifications to the radio and connects to it with only two plugs on the back panel. A circuit board layout is given for those who wish to etch a board; the design can also be wire-wrapped, with no degradation in performance. All normal radio functions - including tuning with normal front panel controls - are still available.

## design considerations

It's best to think of the thumbwheel frequency selector (TWFS) as a unidirectional data source. Yaesu provided an interface to accept commands from an external source on the back panel of the 757, which, among other things, accepts serially encoded binary data as requests for frequency selection options; these are documented on page 10 of the 757 Technical Supplement Manual. In addition to duplicating front panel

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Drive East, Savoy, Illinois 61874
operations, a command is provided for loading any specific frequency. Using this command, discrete frequencies may be entered without all the front panel dial spinning. The 757 never sends data, so no provision needs to be made for data flow from the transceiver.

This circuit sends a prepackaged stream of 50 bits to the radio at 4800 bits per second every time you push a "load" button. The outputs of six BCD thumbwheel switches are part of the 50 -bit stream and indicate what frequency is requested. The thumbwheels provide frequency selection with a resolution of 100 Hz . A two-wire data cable goes from the TWFS to the radio back panel and connects to pins 1 and 2 (the left and middle pins as viewed from the back) of a three-pin connector formally designated as J12 or the EXT CNTL jack. (See pages 9, 10, and 40 of the 757 Technical Supplement Manual for additional details.)

This pair of data wires, carrying TTL voltage levels, is the only connection to the 757 radio that's necessary. But in order to operate the TWFS, a power source providing 5 volts is also required. One additional connection to the 757 back panel provides 13.8 vdc at 800 mA through an RCA phono plug. Using a threeterminal fixed regulator to convert the 13.8 volts provided by the transceiver to a regulated 5 volts, the prototypes were measured to draw 165 mA from the radio. If no other accessories use this connection, it may be used to power the TWFS.

## design details

The schematic for the TWFS is shown in fig. 1. The 555 provides the clock pulses to the 74LS393 at a frequency of 19.2 kHz . The internal $\mathrm{O}_{\mathrm{a}}$ and $\mathrm{Q}_{\mathrm{b}}$ stages of the 393 divide the signal frequency by 4 and the remaining six count-stages provide a 6 -bit binary number updated at the rate of 4800 Hz . The frequency adjustment of the 555 is done with a ten-turn rheostat. Frequency stability of the 555 is sufficient in this application because of the short bursts of data that are sent. For instance, assume that the Yaesu can tolerate a $1 / 8$ bit error in order to read the data correctly. A $1 / 8$ bit error on the 50th bit implies 0.25 percent relative error, allowing a frequency range of the 555 from 19.152 to 19.248 kHz .

The 393 is configured as a 6 -bit counter that automatically shuts itself off when it gets to a count of 50 . Every time the load button is pressed, the counter is reset to zero and counts to 50 one more time. The 6-bit binary number generated by the 393 is interpreted by the three 74150 and one 153 multiplexers so that one of 50 TTL levels are sequentially provided at the output of the 153.

When no data is being sent (i.e., you haven't pressed the load button recently), both address lines to the 153 are high and the HALT signal on pin 13 of

fig. 1. Schematic for the TWFS. Connections for these 48 pins are given in tables 2 and 3.

Table 1. Wiring and data description.

| Bit no. | Data source | Wire to | Description | Bit no. | Data source | Wire to | Description |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 74150A - 8 | 0 | partial bit |  |  |  |  |
| 1 | -7 | 1 | start | 26 | 74150B-21 | p20 | $1 \mathrm{MHz}-1$ |
| 2 | -6 | 1 | $10 \mathrm{~Hz}-1$ | 27 | -20 | p19 | $1 \mathrm{MHz}-2$ |
| 3 | -5 | 1 | $10 \mathrm{~Hz}-2$ | 28 | - 19 | p22 | $1 \mathrm{MHz}-4$ |
| 4 | -4 | 1 | $10 \mathrm{HZ}-4$ | 29 | - 18 | p21 | $1 \mathrm{MHz}-8$ |
| 5 | -3 | 1 | $10 \mathrm{~Hz}-8$ | 30 | -17 | 0 | stop |
| 6 | -2 | p4 | $100 \mathrm{Hz-1}$ | 31 | -16 | 1 | start |
| 7 | -1 | p3 | $100 \mathrm{~Hz}-2$ | 32 | 74150C-8 | p24 | $10 \mathrm{MHz}-1$ |
| 8 | -23 | p6 | $100 \mathrm{~Hz}-4$ | 33 | -7 | p23 | $10 \mathrm{MHz}-2$ |
| 9 | - 22 | p5 | $100 \mathrm{~Hz}-8$ | 34 | -6 | p26 | $10 \mathrm{MHz}-4$ |
| 10 | - 21 | 0 | stop | 35 | -5 | p25 | $10 \mathrm{MHz}-8$ |
| 11 | -20 | 1 | start | 36 | -4 | 1 | $100 \mathrm{MHz-1}$ |
| 12 | -19 | p8 | $1 \mathrm{kHz}-1$ | 37 | -3 | 1 | $100 \mathrm{MHz-2}$ |
| 13 | -18 | p7 | $1 \mathrm{kHz}-2$ | 38 | -2 | 1 | $100 \mathrm{MHz}-4$ |
| 14 | -17 | p10 | $1 \mathrm{kHz}-4$ | 39 | -1 | 1 | $100 \mathrm{MHz}-8$ |
| 15 | -16 | p9 | $1 \mathrm{kHz}-8$ | 40 | -23 | 0 | stop |
| 16 | 74150B-8 | p12 | $10 \mathrm{kHz}-1$ | 41 | -22 | 1 | start |
| 17 | -7 | p11 | $10 \mathrm{kHz}-2$ | 42 | -21 | 1 |  |
| 18 | -6 | p14 | $10 \mathrm{kHz}-4$ | 43 | -20 | 0 |  |
| 19 | -5 | p13 | $10 \mathrm{kHz}-8$ | 44 | - 19 | 1 |  |
| 20 | -4 | 0 | stop | 45 | - 18 | 0 |  |
| 21 | -3 | 1 | start | 46 | -17 | 1 |  |
| 22 | -2 | p16 | $100 \mathrm{kHz}-1$ | 47 | -16 | $\uparrow$ |  |
| 23 | -1 | p15 | $100 \mathrm{kHz}-2$ | 48 | - HALT - | command <br> to load <br> frequency |  |
| 24 | -23 | p18 | $100 \mathrm{kHz}-4$ | 49 | - HALT - |  |  |
| 25 | - 22 | p17 | $100 \mathrm{kHz}-8$ | 50 | - HALT - |  |  |

NOTE: The column headed "Wire to" lists either a header pin number, a " 0, ," or a " 1 ." Header pin numbers 1 and 2 are grounded. Each of the remaining 24 header pins must have a 10 k pullup resistor. " 0 " bits are wired to ground and " 1 " bits are wired to the 580 - ohm pullup resistor. The column headed "Description" indicates how the bit will be interpreted by the 757 transceiver. Remember that the 150 s invert the data.



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Components for thumbwheel frequency selector.
Integrated circuits
7805
555
74LS00
74LS10
74LS393
74LS153
74150
Resistors (all 1/4 watt)
1 580-ohm (pullup for 17 TTL lines)
26 10k (thumbwheel and two switch pullups, $3 \times 9^{\text {SIPS }}$ )
$1 \quad 10 k$ miniature ten-turn potentiometer
3k (555 timing)
1 10k (555 timing)
Capacitors
$0.01 \mu F$ (IC decoupling)
$10.01 \mu$ F ( 555 timing, mylar)
$150 \mu \mathrm{~F}$ (decoupling of 13.8 -volt supply, electrolytic)
$16.8 \mu$ F (decoupling of 5 -volt supply, tantalum)

## Hardware

7805 heatsink
Pushbutton switch, 1-pole, 2-throw BCD thumbwheel switches
1 RCA phono plug (power, 757 connector)
3-pin SIP socket ( 0.1 -inch spacing, 757 connector) 26-pin, 0.1-inch DIP header and socket 3-pin 0.1-inch SIP header and socket
2-pin 0.1 -inch SIP header and socket
1 Cabinet
the 153 is available as data - a TTL high level. As soon as you press the load button, the 393 counter clears to zero and pin 8 of 74150A is sent out as data. Because your button presses aren't synchronized with the clock, this first bit of data may or may not be held for a full $208.3 \mu \mathrm{sec}(1 / 4800)$. That's OK because it's a TTL high signal - the same as the quiescent voltage level. In effect, the bit sequence has started but the 757 doesn't care that the first bit is too short because it doesn't recognize the TTL high level as the first bit.

The next 40 bits (bits 1-40) encode the thumbwheelselected frequency digits. Data is sent in four 8 -bit chunks. Each chunk is prefixed with a start bit (TTL low) and followed by a stop bit (TTL high), yielding a total of 40 bits. Within each 8 bits, two BCD numbers are sent least significant bit first. These numbers are read directly from the contacts of the thumbwheels, necessitating selection of thumbwheel switches with BCD outputs. The frequency is sent least significant digit first. The $100-\mathrm{MHz}$ digit and the $10-\mathrm{Hz}$ digit are permanently wired as zero. The $10-\mathrm{MHz}$ through $100-\mathrm{Hz}$ digits are read from the thumbwheels.

The last 8 -bit value sent is decimal 10 , which indicates to the transceiver that all the previous data should be interpreted as a frequency. The start bit and the first 6 bits of this data are retrieved through the 150/153 multiplex chain as all other bits were. The last 3 bits ( $0,0,1$, sent in that order) actually reflect the status of the counter HALT signal. During the last 3
bits (48-50) the HALT line, which goes high to disable the counter when a count of 50 is reached, is fed through the 153. During counts 48 and 49 , it is false (TTL low); on the 50th count, it goes true (TTL high). Because 555 pulses are locked out with this same signal, the data line stays indefinitely high.

Note that the 150 chip inverts data before passing it to the 153. This is the way most BCD switches work - grounding the logical true pins. Bits 0-47 are sent through the 150s and so are wired inverted. Bits 48-50 (the HALT line) are not inverted by the 153 alone.

## construction

The artwork for a double-sided circuit board is shown in figs. 2 and 3. A parts list is provided. The entire prototype was built using available components, though substitutions may be made. The only critical parts values are in the 555 timer circuit, and even these values could be recalculated to allow use of what you have in stock, following the formulas provided in manufacturers' data books. Although low-power Schottky integrated circuits are called for wherever possible, standard TTL chips would suffice. The power supply drain will increase, but no difference in operation will be noticed.

The circuit is simple enough to be wire-wrapped by hand; in fact, the prototype was wired on two small prototype boards with all the little holes. Provision is made on the pc board for a 7805 voltage regulator and its two bypass capacitors, assuming the 13.8 volt supply from the radio will be used. This portion of the circuit is not shown on the schematic. Refer to a manufacturer's data book or the ARRL's Radio Handbook for details about the 7800 family of regulators. The connections to the 48 data lines of the 150 s are listed in table 1.

Power connections and unused pins for all ICs are tabulated in table 2. I advise the following general order of construction and check-out. Using IC sockets, wire the entire circuit, including all non-IC components. Component placement - following the markings on the circuit board - should be straightforward. Each of the IC positions is marked with a square pad to indicate pin 1. Three columns of ten holes provide a mount for the SIP resistor packages. If SIPs aren't available, mount nine 10k resistors on end, then connect all the tops of the resistors together and into the tenth hole ( 5 volts). Three holes are provided for a horizontal-style ten-turn potentiometer. Two holes relatively close together provide a mount for a radial lead, 13.8 -volt decoupling capacitor, but a larger axial lead capacitor can be mounted by doubling one lead back next to its casing.

Four off-board connections need to be made. The power and data connections are each made with two wire cables. The load switch connects to the board

Table 2. Power connections and unconnected pins for ICs.

| IC | +5 volts | Ground | Not Connected |
| :--- | :---: | :---: | :--- |
| 555 | 8 | 1 | 5 |
| 74LS393 | 14 | 7 | 3.4 |
| 74LS10 | 14 | 7 | $8-11$ |
| 74LS00 | 14 | 7 | $8-10$ |
| 74LS153 | 16 | 8 | $1,3-7$ |
| 74150 | 24 | 12 | None |

with three wires. Each of these connections can use 0.1 -inch space header strips for neatness. The connection to the thumbwheels is made with a 26 -pin 0.1 -inch space dip header. Twenty-five pins are needed (24 BCD data lines and one common ground line); they're listed in table 1.

Install the 7805 regulator. A mounting hole is provided for laying the regulator flat on its back, but it can be left upright if you wish. In either case, a heatsink is suggested. Apply power and verify that the correct voltages are applied to the proper IC socket pins. With the power off, insert only the 555 . Then - with the power back on -- check to see that pin 14 of the 74LS10 socket is receiving an oscillating TTL signal. Adjust the ten-turn potentiometer until a frequency of 19.20 kHz is obtained. Turn the power off.

Install the 393, the 10, and the 74LS00. Apply power again and confirm that pins 2 and 12 of the 393 are stable at a TTL low level. Pressing and holding the load switch should make these pins go to a high level. As you're holding in the switch, pin 1 of the 393 should be receiving an oscillating signal. Release the load switch. Pin 1 should stop oscillating in approximately 10.4 msec (the time needed to send 50 bits). If a digital event counter is available, measure pin 5 of the 393. It should be low while the load button is depressed and count 25 low-to-high transitions when the load button is released. Many frequency counters can be used as event counters by locking their count gate open.
With the power off, install the remaining four ICs. Turn on the power one last time, using the plug on the back of the radio if that's your final intention. At this point, the data output (pin 9 of the 153) should be stable in a TTL high state and a valid 5 -byte sequence of data should appear whenever the load switch is pressed and released. Connect the ground side of the data connection to the left side and the data line itself to the center pin of the three-pin connector on the back of the 757 (J12). Dial a valid Amateur band frequency on the thumbwheels and press the load button. The radio should switch directly to that frequency!

If the transceiver doesn't switch to the requested

Table 3. Bit sequences for two sample frequencies: (A) 10.000 MHz , and (B) 29.999 MHz . The data sent by the TWFS will be interpreted by a normal ASCII computer terminal as the characters listed. Ten ${ }^{H}$ bit groups must be sent with a maximum of 100 msec betwwen them in order to be interpreted correctly by the transceiver.
(A) 10.000 MHz
bits 1-10: 0000000001 cntr -@
11-20: $0000000001 \mathrm{cntrl} @$
21-30: $0000000001 \mathrm{cntrl} @$
31-40: $0100000001 \mathrm{cntrl}-\mathrm{A}$
41-50: 0010100001 line feed
(B) 29.999 MHz
bits 1-10: 0000010011 cntrl-P (8 bit set)
11-20: 0100110011 cntrl-Y (8 bit set)
21-30: 0100110011 cntri-Y (8 bit set)
31-40: $0010000001 \mathrm{cntrl}-\mathrm{B}$
41-50: 0010100001 line feed
frequency after you release the load button, most likely one of the data lines into the 150 multiplexers has been wired incorrectly. If, after careful checking, everything looks correct, the following procedure may reveal the problem. Disconnect pin 3 of the 555 from its IC socket (bend it out horizontally) and plug a slowly oscillating TTL signal (about 4 Hz ) or a low-pulse generator into pin 3 of the socket. Press and release the load switch. A TTL high level should be available as output data. Every four oscillations of the signal generator should cause pin 5 of the 393 to change and the data line to the radio should update. Set the frequency to 100000 and confirm the bit sequence shown in table 3(A). A frequency of 299999 should provide the bit sequence shown in table 3(B).

## conclusion

This should be a fairly simple project for anyone who has worked - even just a little - with digital logic circuits. The idea of simply multiplexing hard-wired data sequentially out a data line is about as simple a communication scheme as possible. I hope others will expand this concept to enable a computer to provide data to the radio. I know useful commercial programs are available, but designs that add greatly to operating convenience don't need to be difficult to do yourself!

Ironically, although l've had fun designing the circuit and building several copies of it, I no longer have a 757 with which to use it. Therefore, I wish to express thanks to Gary LaPook, KA9UHH, for the use of his radio during the design of the project and for proofing the first prototype under actual use conditions. There's a hamfest coming up. I wonder what a used 757 might cost?
ham radio



# ham radio TECHNIQUES 及u or'ssi 

## a new country for you?

We were sitting on the beach in front of the luxury hotel. As cool tradewinds caressed us, we enjoyed a second tall, iced glass of Long Island Iced Tea ( $1 / 3$ each vodka, gin, and white rum, with a splash of cola for color).
"How about going on a DXpedition to a new country?" I asked The Big DXer.
"No way," he replied. "Look at the cost of the Bear Island trip. Activating a new country is too expensive these days."
I gestured toward the horizon. "There's your new country - only a few miles away. You can spend your nights right here in this dandy resort, living it up, and helicopter over and back each day. A 15-minute trip to a new country! Think how many hams you'd make very happy!"
The Big DXer stared at the island. "It looks easy," he said. "What's the trick? Why hasn't it been activated before?"
"Well," I replied, "there's a little problem . . ."
The barren island of Kahoolawe lies a scant dozen miles south of the island of Maui, Hawaii. Uninhabited, it has no water or electric power. Jurisdiction rests with the United States Navy,
much as in the case of Midway Island; the same reasons that Midway is accepted as a separate DX country, then, should be applicable to Kahoolawe.

The "little problem" is that this island is known as the "bombing island" because it's used by the military for bombing and assault practice. The whole surface of the island, it is said, is covered with unexploded ordinance. There's a boat dock, however, with an area around it that's considered safe for occupancy. Armed with a gasoline generator, a transceiver, and a portable antenna, DXers could conceivably operate from this area - if they could obtain permission to land.

Squinting at the island, The Big DXer admitted, "It would be nice to know who in the Navy to approach. Maybe a DXpedition to Kahoolawe is in the cards after all. I'll have another Long Island Iced Tea."

## the 10,18 , and $24-\mathrm{MHz}$ bands

As a result of an ITU conference some years ago, Radio Amateurs were granted operating privileges in narrow bands in the 10,18 and $24-\mathrm{MHz}$ region. Let's look at these bands as they appear in the fall of 1987, together with some simple antennas that will get you on these bands quickly.

Although the 50 kHz -wide $10-\mathrm{MHz}$
band ( 10.100 to 10.150 MHz ) has enjoyed a modest amount of CW activity over the years, it's still largely ignored by most Amateurs. One or two loud commercial stations operating in this range must be avoided, but otherwise the band is good for DX if activity can be found.

It seems to me that in order to awaken general interest in the band, a portion of it should be opened to sideband operation. I therefore propose that the top 25 kHz be opened to sideband. Before the band became available for general Amateur use, I operated sideband on 10.105 MHz with an experimental license for several months; I can attest to the fact that allocating even a small segment of this assignment to sideband would be of great benefit to Amateur Radio. How about a petition in this regard, ARRL?

Although available to Amateurs in over 40 countries, the $18-\mathrm{MHz}$ band ( 18.068 to 18.168 MHz ) is barred to United States hams because of alleged use by the military. But a number of operators monitored this frequency region for several months during the early summer of 1987 - see fig. 1 for a summary of the results of their work.

There's a small amount of overseas Amateur CW operation from 18.068 to 18.075 MHz . Sometimes there's a RTTY signal on 18.070. When it's ac-

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fig. 1. Spread of non-Amateur signals in the $18.068-$ to $18.168-\mathrm{MHz}$ range.
tive, that frequency is avoided. This signal isn't on often, however, and when it's on, it's usually in "idle" mode. The BBC overseas service is quite active on 18.08, and there's a cluster of RTTY and FAX activity from 18.088 to 18.093 MHz .

Two RTTY weather signals are quite active near 18.104, with a multiplex signal slightly higher than 18.120 MHz . Near 18.130 there's a FAX transmission with a "piccolo" signal just above it. There are CW signals near 18.140 and 18.150. At the top of the range, there are several RTTY stations near 18. 165 MHz .

It isn't clear that any or all of these stations are United States military. In fact, some of the signals sound as if they're arriving from overseas. None of them are on continuously except for
the BBC relay transmission on 18.080 MHz , which is very active.

Amateur sideband operation takes place around 18.10 MHz . Stations in Europe, Africa, South America, and Australia have been logged from time to time.

After observing the $18-\mathrm{MHz}$ band for over four years, it seems to me that the military's need for this span of frequencies makes for a pretty thin argument. I propose that the burden of proof of usage be placed on those opposing the presence of United States Amateurs in this band. Merely stating that the band is in use by the military, without proof of occupancy, should not justify the FCC's withholding the band until 1989.

Australia had several government and military assignments in this frequency range. When they opened the band to VK hams, they merely identified certain small spots as "off limits" to Amateur operation. Our govern-
antenna cut to the dimensions shown in fig. 2. Even if you can't transmit on these bands, I urge you to listen, just to get the "feel" of propagation in these interesting portions of the radio spectrum.

## WOSVM's mini-dipole

Amateurs have used miniature antennas on 40 meters for years. The smallest antenna that comes to mind is the loaded 40 -meter mobile whip. Some hams who've placed two of them back-to-back to form a compact dipole (about 16 feet long) have found that the mini-antenna works quite well if it's mounted up in the air.

Even so, the 16 -foot antenna is still too big for some hams who are unlucky enough to be handicapped by location. How about an indoor 40meter antenna?

Jack Sobel wrestled with this idea for some time and finally came up with the antenna shown in fig. 3. He decid-

fig. 2. A "quickie" dipole for 10,18 , or 24 MHz . Feedtine is wound into choke at point it attaches to antenna. Waterproof coax end at antenna.
ment could do the same thing if it wanted to!

The $24-\mathrm{MHz}$ band ( 24.89 to 24.99 MHz ) is in good use and, as the sunspot cycle rises, will quickly become one of the better DX bands. Overseas $D X$ signals pound in, even from stations running low power. Make sure you operate this band during the fall and winter DX season!

You can get on the 10, 18, and $24-\mathrm{MHz}$ bands quickly with a dipole
ed to use a long, thin radiating coil, or helix. Many hams frown on the helix antenna, but Jack and others have had good luck with the configuration.

Since material was at hand to make an antenna about 2 feet long, he decided this length would be a good place to start. The idea was to wind the antenna into a helix, or coil, and then place a matching coil at the center. Because the radiation resistance of the helix was bound to be
very low, Jack chose a tapped matching coil technique to approximate a match to a 50 -ohm line. And since antenna $Q$ would be very high, he decided to use a Transmatch at the station end of the transmission line.

## construction details

The antenna can be wound on a cardboard mailing tube. Coils L1 and $L 2$ are 10 inches long and wound at six turns per inch ( 60 turns per coil of No. 12 AWG insulated wire). Coil L3 is 5 inches long and wound at six turns per inch ( 30 turns) of No. 12 tinned wire. Coil L3 is wound in the direction opposite to the direction in which coils L1 and L2 are wound. The braid of the coax line is attached to the center point of L3, and the center conductor is tapped out until a match is found to provide the lowest value of SWR at the resonant frequency of the antenna. Resonance is established with the aid of a dip meter before the antenna is attached. The tap point is about $2 / 3$ the distance from the center to one end of L3. (The exact point depends upon the coupling between the antenna and nearby objects and the exact spacing of the windings.)

The antenna is fed with an electrical half-wavelength of RG-58/U coax. The line can be coiled up if it's too long to fit the available space.

The passband of the antenna is quite sharp, and if operation across the 40-meter band is desired, a Transmatch is necessary at the transmitter end of the line.

The antenna should be sprayed with a transparent polyurethane material or "corona dope" (a cellulosic resin such as General Cement's No. 10-4702). So far, the antenna has been run only at low power levels; since there may be danger of corona discharge at the outer ends of the windings, it's best to use the spray coating to help prevent this.

The antenna should be mounted as high in the air as possible and placed in a position where it can't be touched. There's very high rf potential at the ends of the little antenna, and an unsuspecting person could get a nasty rf

fig. 3. The mini-antenna of WOSVM. Adjust coax tap for best SWR at resonance.

burn during transmitter operation.
If more space is available, two mailing tubes can be epoxied together and the turns-per-inch increased so that the antenna covers more length along the longer tube. The winding will have to be readjusted to frequency with a dip meter if this change is made.

So far, Jack's contacts have been limited to a few hundred miles on 40 meters. He says it isn't as good as a full-size dipole, but it's small and can be used in an apartment.

## a communications speaker system

Tired of listening to that annoying high-frequency "monkey chatter" that
seems to sneak through the receiver filter system? It can be extremely tiring, especially in a DX contest. The VK boys seem to have a handle on that problem. Rodney Champness, VK3UG, writing in the March, 1987, issue of Amateur Radio, the publication of the Wireless Institute of Australia, shows a simple audio filter that can be placed in the speaker line (fig. 4) to substantially reduce frequencies above 2500 Hz . A switch on the filter allows normal wideband reception to be retained.

The $1-\mathrm{mH}$ inductor should be able to carry the audio current in the speaker circuit (something less than 1 ampere).
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# PRACTICALLY SPEAKING <br> ... $)^{\text {as }}$ <br> KAIPV 

## using voltage comparators

A voltage comparator is basically an operational amplifier (or derived from the op amp) that has no negative feedback network (see fig. 1A). The openloop gain of the op amp is very high - on the order of 50,000 at the low end to more than $1,000,000$ for many devices. Thus, with no negative feedback the operational amplifier functions as a very high-gain amplifier with an output that saturates with only a few millivolts input potential. For example, with a gain of 100,000 , and a maximum output potential of 10 volts, the amplifier will saturate with only 10 volts $/ 100,000$, or $0.1-\mathrm{mV}$ input.

So what use is an amplifier that saturates with only a few millivolts of input voltage? The comparator is used to compare two input voltages and generate an output that denotes their relationship. In fig. 1A, potential $V_{1}$ is applied to the inverting input, and $V_{2}$ is applied to the noninverting input. If $V_{1}=V_{2}$, then $V_{0}=0$. Otherwise, the output voltage obeys the relationships shown in fig. 1B. The transfer function of the comparator is shown in fig. 1B. According to the normal rules for operational amplifiers, when $V_{1}$ is larger than $V_{2}$ (see fig. 1A), it looks as if a positive input has been applied to the inverting input, so the output potential saturates at V -. Alternatively, when $V_{1}$ is smaller than $V_{2}$, it looks like a negative input potential, so the output is $V+$.

Typical Amateur examples include
over- and under-deviation alarms on repeater receiver detector outputs, and over-temperature alarms for electronic equipment. For example, some form of alarm is needed at unattended repeater sites. The comparator can be used to let the control operator know by telephone or radio telemetry link that something is amiss. Other applications will occur to most readers in the light of their own special needs.

There is a small hysteresis band around zero, however, where no output changes occur. This is an unfortunate defect in practical op amps, and seems to fly in the face of the theory when that hysteresis band is larger than the potential needed to saturate the output terminal.

Several years ago, while working in a hospital electronics lab, I measured the hysteresis band on a number of operational amplifiers and IC comparators (LM-311). Not surprisingly, the 741 -family devices had terrible hysteresis levels, on the order of 25 mV . The LM-311 devices had 8- to $10-\mathrm{mV}$ hysteresis, which surprised me. Also surprising was the fact that then-premium devices such as the $\mu \mathrm{A}-725$ had 10 to 20 mV of hysteresis (1 haven't tested modern high-performance units). The overall best device was a non-premium device that is readily available to Amateurs and other hobbyists: the CA-3140 (a BiMOS operational amplifier), which uses the industry standard " 741 " pinouts, as shown in fig. 1A.

The LM-311 device (fig. 2A) is a low-cost voltage comparator in IC form. Although based on op amp cir-

fig. 1. (A) Simplified diagram of voltage comparator; (B) comparator transfer characteristic.

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fig. 2A. LM-311 voltage comparator.
fig. 2B. Zeners improve transfer characteristic and speed, and limit output voltage of the comparator.
cuitry, this device is specifically designed as a comparator. Contrary to op amp practice, it has a ground terminal (pin 1) and requires an output pull-up resistor ( R ) to a positive voltage. The output terminal can drive loads such as relay coils, lamps, and LEDs to potentials of 40 to 50 volts (depending upon the type of device) and 50 mA . If the LM-311 is operated for compatibility with TTL digital logic, the pull-up resistor should be terminated at a +5 VDC potential, and $R$ should be 1 to 3.3 k .

A means for limiting the output level, improving the sharpness of the transfer function corners (see fig. 1B), and improving speed by reducing latch-up problems, is shown in fig. 2B. In this circuit, two zener diodes are connected back-to-back across the output line. When the output voltage is HIGH, it is then limited to $V_{Z 1}+0.7$ volts; when LOW, it is $V_{Z 2}+0.7$ volts. These potentials represent the zener voltages of $C R_{1}$ and $C R_{2}$, plus the normal forward-bias voltage drop of the alternate diode.

Figure 3 shows a means for increas-
ing the drive capacity of the comparator. In this circuit a switching transistor (a 2N3704, 2N2222, etc.) is used to control a larger load such as the relay coil shown here. The output voltage ( $\mathrm{V}_{0}$ of the comparator) is used to set up the bias for the NPN transistor. When the comparator output is HIGH, the transistor is biased hard-on and the load is grounded. Alternatively, when the comparator output is LOW, the transistor is reverse biased and the load remains ungrounded.

The diode across the relay coil is essential for any inductive load. When the magnetic field surrounding a coil collapses the counter EMF generates a high-voltage spike that is capable of damaging components or interrupting circuit operation (especially digital circuits). Though the diode is normally

fig. 3. Addition of switching transistor allows higher current loads to be controlled.

fig. 4. Two methods of reducing the hysteresis band effect: zero offset control and current mode operation.

fig. 5. Zero crossing detector circuit and waveforms.
reverse biased, it is forward biased for the counter EMF spike. The diode therefore clamps the spike to about 0.7 volts.

Figure 4 shows two methods. One is a zero-offset control used to reduce the effects of the hysteresis band, while the other is the so-called current mode. The offset control $\left(\mathrm{R}_{4}\right)$ slightly biases one input to a non-zero level so that it's ready to trip when the other input is non-zero. In this particular case the inverting input is grounded $\left(\mathrm{V}_{2}=\right.$ 0 ), but could as easily be a non-zero voltage.

Current mode operation is usually faster and less prone to latch-up than voltage mode. For this reason, current mode comparators are sometimes used in high-speed analog-to-digital converters (A/D). Assume that the noninverting input is grounded. In this case, the output potential $V_{0}$ will reflect the relationship of the two currents. If $I_{1}=I_{2}$, then $V_{0}=0$. This circuit is, to the outside observer, a voltage comparator in that $I_{1}=V_{1} / R_{1}$ and $I_{2}=V_{2} / R_{2}$. Of course, it's also useful for current output devices such as the LM-334 temperature monitor IC.

fig. 6. Window comparator triggers on two different reference levels being exceeded.

Figure 5 shows a zero-crossing detector circuit. In this case a comparator is connected with its noninverting input grounded. When $\mathrm{V}_{\text {in }}$ is non-zero, then the output will also be non-zero. But when the input voltage crosses zero, the output briefly goes to zero, producing the differential output pulse shown.

A window comparator is shown in fig. 6. This circuit consists of two comparators connected so that one or the other input is activated when the input voltage ( $\mathrm{V}_{\text {in }}$ ) exceeds either positive or negative limits. The limits are determined by setting $\mathrm{V}_{1}$ or $\mathrm{V}_{2}$ reference voltages. An over- and underdeviation alarm, as heard on some repeaters, is a possible application for this circuit. The output of the fm demodulator is a voltage that is proportional to deviation, so this circuit is a natural for that use (although the demodulator voltage will probably require some amplification). The circuit is also used for over- and under-temperature alarms, and other such applications where a range of permissible values exists between two forbidden regions.

Figure 7A shows a method for biasing either input to a specific reference voltage. Although in this case the noninverting input is biased and the inverting input is active, the roles can just as easily be reversed. Two methods of biasing are used: resistor voltage divider and zener diode. If $\mathrm{R}_{2}$
is replaced with a zener diode, then the reference potential is the zener potential. In that case, $\mathrm{R}_{1}$ is the normal current-limiting resistor needed to protect the zener from self-destruction. In the case where a resistor voltage divider is used, the bias voltage $V_{1}$ is set by the voltage divider equation:

$$
\begin{equation*}
V_{1}=\frac{R_{2}(V+)}{R_{1}+\frac{R_{2}}{2}} \tag{1}
\end{equation*}
$$

For example, suppose $R_{1}=R_{2}=$ 10 k , and $\mathrm{V}+=12 \mathrm{VDC}$ :

$$
V_{I}=\frac{(10 k)(+12 V D C)}{(10 k+10 k)}
$$

$$
V_{I}=\frac{120 \text { volts }}{20 k}=6 \mathrm{volts}
$$


fig. 7. (A) Method of biasing comparator to a specific reference voltage; (B) overtemperature sensing circuit is biased by $R_{1} / R_{2}$ resistor combination.

Figure 7B shows an over-temperature circuit based on fig. 7A. In this circuit the inverting input is biased by $R_{1} / R_{2}$, while the noninverting input is set by another voltage divider, $\mathrm{R}_{4} /$ $\mathrm{RT}_{1}$. Resistance $\mathrm{RT}_{1}$ is a thermistor, which has a resistance proportional (or inversely proportional in some types) to the temperature. Potentiometer $\mathrm{R}_{4}$ is used to set the trip point temperature. The values of the resistors depend upon the set trip point desired and the resistance of the thermistor over the range of temperatures being monitored.

## an invitation

I'd like to hear what you think of this column. I also welcome your suggestions for future topics. You can reach me at P.O. Box 1099, Falls Church, Virginia 22041.
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# DX FORECASTER 

## Garth Stonehocker, K0RYW

## winter DX

With the fall DX season (September and October) behind us, the winter DX season (November through February) is about to begin. Wintertime DX is characterized by:

- Better signal strengths on all bands most of the time - but especially during daytime on the lower frequencies, particularly in low sunspot years. - Nighttime DX openings earlier in the evening.
- More frequent transequatorial paths, with higher MUFs and longer distances.
- Lower incidence of local thunder-storm-generated QRN conditions.
- More stable signal strengths and fewer geomagnetic field disturbances.

There are two main reasons for the first four characteristics: the tilting of the Earth's axis away from the sun, which results in shorter, colder days; and less ionization in the lower ionosphere, which results in less energy absorption as signals travel through the D region.
The amount of absorption per hop is related to the zenith angle to the sun at the location of each D region crossing. In working $D X$, it pays to use a higher frequency band to obtain more distance per hop (resulting in fewer transits) for less total signal loss. This is why we generally think of 6,10 , or 15 meters for DXing.
But in winter, particularly near sunspot minimum, we have the opportunity to work DX on the lower frequency bands with lower signal loss, day or night, than at any other time of the year. You can't always count on it,
however; signals traveling a high latitude path may be poor for several days at a time. This is known as the winter anomaly.

Along with lower signal attenuation, ORN decreases as fewer local thunderstorms pass through. As the large thunderstorm areas near the equator move further south, their noise decreases by about 6 to 8 dB . This is particularly noticeable on the 160,80 , and 40 -meter bands.

Even though ion production in the $D, E$, and lower $F$ regions is lower, ions are better able to diffuse and drift upward along the geomagnetic field lines into the F region. This layer is the major factor in defining the maximum usable frequency and maximum on each side of the geomagnetic equator, as shown in my October, 1983, column. These maximums, which are reached most evenings at about 2200 local time, eliminate one whole earth bounce and its accompanying doubleD region transits for one-long-hop propagation.

The fifth characteristic of winter DX conditions - the increased stability of signal strengths and the decrease in the number and intensity of geomagnetic field disturbances -- is attributable to the eccentricity of the Earth's orbit. When the Earth is closer to the sun, the solar flux pressure on the magnetosphere surrounding the earth tends to hold the magnetosphere steadier. This means that the geomagnetic field is least disturbed during November and December. This manifests as least variation of the magnitude and direction
of the geomagnetic field lines in an hour's time, translating into fewer periods of OSB during these months.

## last-minute forecast

The higher-frequency bands are expected to be best during the first two weeks of the month because of the probability of higher solar flux at that time. The new 11 -year solar cycle is also expected to be well underway, with higher solar flux from the more active regions. More potent geomagnetic storms may accompany this increased activity, but they're not really expected during this quiet time of the year and at this point in the sunspot cycle. The most probable times of the month are November 2, 11, and 20. The lower bands are expected to be best the third week of the month. Thanksgiving weekend should be a good one for the whole frequency range.

The Taurids meteor showers will occur from October 26 to November 22, with a maximum count of ten per hour from the 3rd through the 10th of November. Lunar perigee is on the 5 th.

## band-by-band summary

Ten and twelve meters, the highest day-only DX bands, are nearest the MUF for southern hemisphere paths. They will be open most days when the solar flux is above 75 during the 3 - to 5 -hour period centered on local noon. These bands open on paths toward the east and close toward the west. The paths are up to 4000 km ( 2400 miles) in single-hop length, and on occasion double that during evening transequatorial openings.

Fifteen meters, a day-only DX band open most of each day, has lower signal strengths and greater multipath variability than 10 and 12 meters. It will be best when the MUF is resting just above this band, until it drops below it - a transition period that occurs


[^0]"Look at next higher band for possible openings.

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Transmission Line Transformers covers types of windings, core materials, fractional-ratio windings, efficiencies, multiwinding and series transformers, baluns, and limitations at high impedance levels. There is also a chapter on practical test equipment. This book is must reading for everyone interested in antenna and transmission line theory. Copyright 1987, 128 pages $\$ 10$ hardcover only.
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## an rf voltmeter

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Many of us who experiment with circuits need to measure the level of signal sources such as oscillators, amplifiers and multipliers in transmitters, and local oscillator systems in receivers. The voltmeter design described in this article came about when I wanted to measure the voltage reflection coefficient of antenna systems using a return loss bridge at low levels so as not to interfere with other band users.

The common method of measuring signal levels is through the use of a simple diode detector. In its basic form, however, it has a number of shortcomings, some of which can be easily overcome.

## voltmeter requirements

This voltmeter covers a range from less than 70 millivolts to greater than 3 volts rms (equivalent to -10 to +23 dBm in a 50 -ohm system), covers a frequency range from 10 kHz to 150 MHz , and provides readings accurate to within $\pm 2 \mathrm{~dB}$ without calibration - i.e., as built and tested. Its input impedance is set by the input resistor; a value of 50 ohms was used in the models shown. Its output is linear; if an analog meter is used, no special marking of the meter scale is necessary. An external general-purpose meter can also be used. The meter draws less than 15 mA from a pair of 9 -volt transistor batteries.


## diode detectors

The characteristics of an ideal linear voltage detector are illustrated in fig. 1. This mythical device conducts current in one direction only, with a low and constant resistance when forward biased and an infinite resistance in the reverse direction. The constant forward resistance is maintained right down to 0 volts,


By lan Braithwaite, G4COL, 28 Oxford Avenue, St. Albans, Herts, AL1 5NS, England

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fig. 2. Unbiased single diode detector: (A) schematic (B) waveforms at " $a$ " and "b."

fig. 3. Two-diode biased detector.
with an abrupt transition to the reverse region. Such a device used as a rectifier would deliver a dc output proportional to the applied ac.
Real diodes, however, don't behave this way. Most do not conduct appreciably in the forward direction until the input voltage across them exceeds a threshold or "knee" voltage, which for an ordinary silicon junction diode is around 0.7 volts. The threshold voltage for germanium and Schottky diodes is lower 0.2 to 0.4 volts. Real diodes also conduct slightly in the reverse direction (the so-called reverse leakage current).
The transition between the conducting and nonconducting states is not sharp, but occurs over a region where the diode is said to have "square law" behavior and the dc output is proportional to the applied power (voltage squared), rather than the signal voltage. This is used to advantage in low-level diode power meters.

To see how real detectors behave, I made some measurements on a few types using a crystal oscillator signal source at 10 MHz , and a power meter and attenuator to give a range of calibrated levels. Figure

2 shows the first test circuit, a simple peak detector using an HP2826 Schottky diode. The right-hand plate of the input capacitor is clamped at the diode knee voltage below ground on negative input swings. If this knee voltage were actually zero, the average voltage on the diode would equal the peak of the input voltage, but the real diode produces less. The resistor and capacitor filter the if present on the diode, leaving the dc component. This can be measured by a high impedance meter which reads the peak of the rf voltage minus the diode knee voltage.

A dc forward bias current can be used to improve the sensitivity of the diode detector. If the diode is fed from a high resistance with a current of a few $\mu \mathrm{A}$, its forward junction voltage will sit around the knee voltage. This potential no longer has to be supplied by the rf, which sweeps the diode's nonlinear characteristic and is detected. Direct current bias is used in the more sophisticated circuit shown in fig. 3. Two diodes are used. Both are biased, but rf is fed to only one of them. An op-amp subtracts the diode voltages so that the output of the circuit can be set to zero in the absence of an rf signal. With the diodes connected together, with no rf, the op-amp offset is nulled. The $500-\mathrm{k}$ pot is then adjusted to give zero output with the circuit exactly as drawn. The circuit works best with matched pairs of diodes, since these track well with temperature.

The performance of these detectors is described graphically in fig. 4. This shows the improvement in sensitivity achieved with bias. Also shown is the curve for the voltmeter design, which indicates further improvement in sensitivity and linearity, gained by using just one additional technique.

The complete of voltmeter is shown in the block diagram in fig. 5. Two detectors are used. One receives the incoming of signal, while the other, a "mimic" detector, is fed with a low frequency signal. This signal is an internally generated sinusoid, derived by chopping the dc output of an integrator to give a square wave which is then filtered, leaving the fundamental frequency component.

The integrator input is the difference of the two detector voltages, and its output will change (or "slew") when this difference (the feedback loop's error signal) is other than zero. The action of the negative feedback loop around the mimic detector in fact causes the integrator to try to achieve this zero-error condition, at which point, if the detectors are well matched, the low frequency signal will have the same amplitude as the rf signal. Because the low frequency signal is produced by chopping and filtering the integrator's dc output, this latter voltage is proportional to the rf input voltage, and can be scaled and metered to provide readings in "rf" volts.

Through the use of well-matched and closely spaced

fig. 4. Detected dc output versus applied rf input: (A) single unbiased diode detector; (B) biased diode detector; (C) if voltmeter; (D) ideal rf voltmeter.

fig. 5. Voltmeter block diagram.
diodes, their temperature and I-V curve variations are minimized. Of course, since the mimic detector measures only a fixed low frequency signal, no frequency response compensation for the input detector is provided. Therefore, it's best to choose the diode that has the flattest possible response.

fig. 6A. Voltmeter schematic diagram.



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## circuit description

RF enters the instrument via socket SK1. R5 and R6 provide a good impedance match to 50 -ohm cable. Two 0.5 -watt metal film resistors (or any other combination providing 50 ohms and a 1 -watt rating) should be used. Diodes CR1 and CR2 form the detectors: CR1 is supplied with rf, and CR2 with the internally generated $25-\mathrm{kHz}$ sine wave. They should be Schottky diodes and, if possible, should be reasonably well matched in terms of forward voltage at around $10 \mu \mathrm{~A}$. Many types will do, among them the HP2800 and 2826 and the Thomson BAR28. The forward voltage will be in the region of 250 mV , and a pair matched to within a few millivolts can often be found from a small batch. Circuitry around U4 performs subtraction of the two detector outputs with a gain of 10. R14 allows U4's offset voltage to be nulled. Because this is a relatively high gain stage, the remaining stages do not need to be nulled, and can be grouped into a quad package. U5B is wired as an integrator, and CR3 and buffer U5C prevent the CMOS switch U3 from being driven negative. The buffer's dc output is chopped by switch U3, which is operated by $25-\mathrm{kHz}$ square waves from U2, a divide-by-2 flip-flop fed from U1, a $50-\mathrm{kHz}$ oscillator. U2 could be omitted and U1 run at 25 kHz , but U2 does achieve a perfect square wave (1:1 mark-tospace ratio) at small cost. U2B provides a $12.5-\mathrm{kHz}$

output signal so that a rough check can be made on the switching signal with a crystal earpiece at test point C. The chopped dc from U3, now a $25-\mathrm{kHz}$ square wave with a peak-to-peak amplitude equal to the U5C dc output, is filtered by active filter U5A (second order bandpass) so that CR2 receives a fairly sinusoidal signal. L1 was included to stop hf oscillations in the output stage of U5A when the connection to the detector was completed via several inches of ribbon cable (the adjacent wire being grounded). It consists of four turns of enameled wire on a single-hole ferrite bead (I used an FX1115), and has no measurable effect at 25 kHz . R18 and R19, buffered by U5D, attenuate the dc by a factor of 0.45 (see appendix for derivation), which provides scaling to units of volts rms. An external voltmeter plugged into SK2 will then read the if input voltage. R21 and R22 with switch S2 allow the use of a meter to read 1 and 10 volts full-scale. With 9 -volt supplies from batteries, the maximum voltage that can be read will be around 3 volts.

## construction

I have built three instruments according to the design described in this article (see fig. 7). The outer two are battery powered (internally); the "economy model" in the center uses an external power supply and meter. Details of the unit on the left are shown in figs. 8A, $\mathbf{8 B}$, and 8 C . Construction is straightforward and can be done with ordinary hand tools. The only critical area is the detector, which carries if. The other areas involve only low frequency circuitry. As shown in fig. 8C, I built the input circuitry, consisting of the two detector diodes and $U 4$, on a small piece of doublesided, copper-clad glass-fiber board, using a counterbore tool to provide pads for the components. Frankly, this method of construction - with the components mounted rats-nest style above a copper ground plane, will work at least as well and probably better than a pc board, and is certainly much faster. Those willing to make a pc board for the voltmeter are welcome to do so - I'm afraid I'm too lazy!

The rest of the circuit is wired on a perforated breadboard with copper strips on the underside (known in the UK as "Veroboard"). As the photo of the detector board shows, the signal connection from the front panel socket was made using RG-178 coaxial cable. The only place it's important to keep leads as short as possible is in the detector area. Try to mount the two diodes close to each other for good thermal tracking.

## alignment and testing

Check the $50-\mathrm{kHz}$ oscillator and divider by placing a crystal earpiece or high impedance audio amplifier between test point C and ground. The frequency can now be adjusted to coincide with the bandpass filter.


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fig. 7. Three different packaging approaches for the same voltmeter.

Turn R9 or R14 so that U4 output is slightly negative, which will cause the integrator U5B to slew to the positive limit. This should result in a healthy square wave output from U3 (pins 1 and 2). A high impedance meter should read a voltage (dc) here that is half that at the U5C output. If the meter is transferred to the anode of CR2, it should be possible to peak this voltage by adjusting the oscillator frequency control R4.

The detector circuit can now be set up with no input. Ground test point A to stop the 50 kHz oscillator. Connect CR1 and CR2 so that the subtractor sees the same voltage at both its inputs. Set test point $B$ to zero volts with R14. Remove the connection between the diodes, and again zero-test point $B$, this time with R9.

If if is now applied, U5C should go positive, and the voltage at the output socket SK2 should be 0.45 of this. The meter is now ready to use.

## performance

The absolute accuracy and linearity of this meter is illustrated in fig. 4, which was constructed from measurements made at 10 MHz . The flatness with frequency was measured at $1 \mathrm{~mW}, 224 \mathrm{mV}$ rms ( 0 dBm ), and the results are shown in fig. 9, which represents a respectable performance of within $\pm 3$ percent up to 150 MHz . This could no doubt be improved to extend the useful range to 70 cm and beyond.

To verify the repeatability of these measurements, I tested the three units against each other using the same source, a $10-\mathrm{MHz}$ crystal oscillator. Referring to the units by position in the photo, the results were:
Unit Reading on external voltmeter
Left $\quad 268 \mathrm{mV}$
Center 244 mV
Right 258 mV
Obviously, three is only a small sample, but considering that the voltmeters had received only the simple dc setup procedure described earlier, I was quite pleased with the outcome, and I hope that this sort of performance will be adequate for your applications.

## further suggestions

I hope that readers who build this voltmeter will find it a handy instrument to have around the shack. Those who like to experiment and develop their own hardware might enjoy exploring the following options:


A


B


C
fig. 8. Internal views of the rf voltmeter: $(A)$ internal power provided by two 9 -volt batteries; (B) "clean" construction enhanced by use of Veroboard; (C) "rf" section of voltmeter.

9 Autry


[^1]
fig. 9. Flatness with frequency at 0 dBm .

- The design can be simplified by omitting the divider U2. The oscillator could then be run at 25 kHz , or the filter redesigned for 50 kHz . (The choice of frequency was somewhat arbitrary, being high enough to use small coupling capacitor C3 and low enough for active filtering. U2 does guarantee an excellent square wave, but the oscillator alone may well be adequate.)
- The detectors can be built into a high-impedance probe for circuit tracing, rather than a 50 -ohm instrument. Keep CR1 and CR2 physically and electrically close together, though.
- By paying attention to the detector matching and circuit offsets, particularly around U4, the useful range could be extended downwards. With attenuators, the range could be extended upwards.
- Careful selection of devices and construction could greatly extend the frequency range.
- The filtering of the square waves could be improved. The units I have built tend to read slightly high, and this could be because the active filter output is not a pure sinusoid, giving a slightly wrong scaling factor. Why didn't I just feed CR2 with a raw square wave? Well, when I tested a diode detector using an accurate function generator, the peak readings were different between sine and square waves - i.e. the diode appeared to clamp at slightly different voltages, depending on the waveform. I wish I knew why; in any case, the results might be worth repeating. If CR2 gave the same response to square waves, the active filter could be omitted. U5C output would then be the peak input voltage, and scaling by 0.707 would give readings in volts rms.

fig. A1. Relationship between a square wave and its fundamental sinusoidal component.


## appendix

how readings are scaled to volts rms
The voltmeter works by making an internally generated sine wave derived from filtering a square wave equal to the rf input. The square wave, then, is generated by chopping a dc voltage. As illustrated in fig. A1, Fourier theory tells us that the fundamental (sinusoidal) component of a square wave has a larger peak amplitude than the square wave itself (don't worry, there is less power in this sine wave). If we call the peak amplitude of the sine wave $V_{\text {sine }}$ and the peak-to-peak amplitude of the square wave $V$, then;

$$
V_{\text {sine }}=\frac{2 V}{\pi}
$$

But in the voltmeter circuit, the peak-to-peak square wave amplitude is equal to the integrator's dc output voltage $\mathrm{V}_{\mathrm{dc}}$, that is:

$$
V=V_{d c}
$$

We want to make the voltmeter read rms volts. If the applied rf has an rms voltage $\mathrm{V}_{\mathrm{in}}$, then the feedback loop makes:

$$
V_{\text {sine }}=\sqrt{2} \quad V_{i n}
$$

So, the quantity we want to measure, $\mathrm{V}_{\text {in }}$ is given by:

$$
V_{\text {in }}=\frac{V_{\text {sine }}}{\sqrt{2}}=\frac{\sqrt{2} V_{d c}}{\pi}=0.45 V_{d c}
$$

This is why the dc produced by the integrator is scaled by 0.45 .

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# VHFUHF WORLD 

## low-noise receiver update: part 1

"You can't work 'em if you can't hear 'em" is an old adage that's still very true. Building bigger and better antennas helps, but sooner or later the antenna size limitation places the burden on the receiver.
Only a decade ago, most Amateurs were using bipolar transistor preamplifiers on the front ends of their VHF and lower UHF band receivers. On the upper UHF and lower SHF bands, diode mixers without preamplifiers were common - with typical noise figures of 6 to 10 dB ! That's all changed now, first with the arrival of low-noise silicon bipolar transistors capable of operation into the GHz region, and then with the introduction of GaAs (Gallium Arsenide) FETs in the late 1970s. ${ }^{1}$
Since reference 1 was written, there have been many new and startling developments in the area of low-noise devices and techniques. Noise figures are still dropping; device prices have stabilized. So this seems like an appropriate time to update the earlier material and to present state-of-the-art (SOA) information.
This month's column will serve as a quick review and update of the present

SOA in low-noise receiver technology. Next month's column will be devoted more to low-noise circuit techniques, recommended devices, testing, and optimization. With all this information in place, you should be right on the cutting edge of low-noise receiver technology.

## a quick review

The SOA in VHF/UHF and microwave low noise figure Amateur receivers and preamplifiers is now dominated by GaAsFETs, which are technically classified as Metal Semiconductor FETs (MESFETs). The term MESFET is used in the professional community because the gates of a GaAsFET are formed using aluminum, which is a metal that is in direct contact with the semiconductor material. Thus a Schottky barrier diode is formed in the N -type material as shown in fig. 1A.
When the lowest noise figure is required above about 100 MHz , GaAsFETs are favored over silicon bipolar transistors because they have up to five times faster electron mobility. Hence, GaAsFETs have much higher cutoff frequencies and gain than silicon bipolar transistors. Furthermore, they typically have much lower noise figures.

Reference 1 , an introduction to lownoise GaAsFET technology, gave de-
tails on preamplifier designs for 144 , 220 , and 432 MHz , with suggestions for higher-frequency operation. When this material was published in 1984, the GaAsFET was king, but that's no longer true; lower-noise devices and new breakthroughs in technology now threaten to decrease noise figures so far that they will no longer be the primary limitation to communication capability. Stay tuned.

In addition, during the last few years there's also been a proliferation of "mast-mounted" low-noise preamplifiers using GaAsFETs. These preamps almost completely eliminate the losses associated with feed lines, and virtually eliminate the mismatch loss associated with feed line losses. ${ }^{2}$ This is a major problem with low-noise preamplifiers because they often have high input VSWR.

## latest developments in devices

GaAsFETs were originally used in commercial and government low-noise amplifiers operating above 2 GHz . Amateurs were in the forefront of developing low-cost GaAsFET preamplifiers to frequencies as low as 30 MHz , but these devices were practical mainly on 2 meters and above, where ambient and sky noise are low. ${ }^{3}$

GaAsFETs are now being used commercially through 40 GHz and possibly

fig. 1. Typical physical structures (not shown to scale) of GaAsFETs and HEMTs: (A) depletion mode GaAs FET; (B) depletion mode HEMT.
higher. New lower noise figure, higher gain, and cutoff frequency devices seem to be appearing almost monthly. Needless to say, if you want to be on the cutting edge of technology, you might as well use any premium-quality devices you have in your desk drawer as soon as possible - before they become obsolete! GaAsFETs with noise figures less than 1.0 dB are now available through 4.0 GHz ! SOA GaAsFET noise figures versus frequency are shown in fig. 2.

Probably the most important recent improvement in the SOA in low-noise devices is the development of the HEMT (high-electron-mobility transistor). ${ }^{4.5}$ Sometimes referred to as TEGFETs (two-dimensional electron GasFETs) ${ }^{6}$ or heterojunction FETs (to avoid infringing the copyright on the name HEMT in Japan). Technically speaking, the HEMT is a heterojunction superlattice device that was first described in 1978 and demonstrat-
ed by Fujitsu and Thompson-CSF in 1979. ${ }^{4.5 .6}$ It is very similar in structure to the GaAsFET except for the twodimensional electron gas as shown in fig. 1B.

The HEMT's major feature is, typically, its higher transconductance with a cutoff frequency twice that of a comparable GaAsFET, with higher gain and noise figures as low as half those of typical GaAsFETs! Cutoff frequencies well above 100 GHz have been reported. HEMTs with less than $1.0-\mathrm{dB}$ noise figures are now available through $X$ band ( 12 GHz ). The SOA in HEMT noise figures is shown in fig. 2.

Right now, however, most HEMTs are laboratory devices, and the lowest noise devices are very scarce. Only a few HEMT types are available commercially, and these devices are expensive -- typically more than \$150 each! However, remember that GaAsFETs were in the same price range in the mid-1970s, and better devices are now
available for less than $\$ 5$ ! HEMTs are known to be manufactured by Fujitsu, GE, Gould-Drexel, NEC, Sony, Thomp-son-CSF, Toshiba, TRW, and Varian Associates. Other suppliers and even lower noise figures are promised!

Unlike other innovations in technology, the HEMT is compatible with existing GaAsFET dc biasing and rf characteristics. HEMTs usually use the same packages and can be virtual "drop-ins" for GaAsFET circuits. The primary difference is that the HEMT's optimum source impedance is generally higher than an equivalent GaAsFET's. Therefore, an adjustable inputmatching circuit similar to the one described in reference 1 is recommended so that the optimum source impedance can be achieved.

One major MESFET anomaly should be stressed. As pointed out in reference 1, GaAsFETs (as well as HEMTs) have a very high noise figure in the socalled $1 / f$ or low-frequency region. This

fig. 2. Typical 1987 state-of-the-art noise figures of bipolar transistors, GaAsFETs, and HEMTs: (A) uncooled bipolar transistor; (B) low-frequency GaAsFET at room temperature; (C) high-frequency GaAsFET at room temperature; (D) HEMT at room temperature; (E) GaAsFET cooled to 12 degrees Kelvin; (F) HEMT cooled to 12 degrees Kelvin.
means that the noise figure increases not only as you increase frequency, but also as frequency is decreased! This effect is shown in fig. 2.

The amount of noise figure increase and the frequency where it begins to increase (below the normal operating frequency) depends on the device type. Generally speaking, the ideal rf operating region for GaAsFETs and HEMTs is over a one decade-wide frequency range referenced down from the specified operating frequency (not the $F_{\max }$ ).

For example, a device specified for $1-\mathrm{GHz}$ operation at the top of its operational frequency range will probably be well suited for operation down to about 100 MHz . However, a device specified for 10 GHz will probably have a higher noise figure if it's used much lower than about 1 GHz !

Therefore, don't expect that a very low-noise GaAsFET specified for 10 GHz will be a super low-noise device at 144 MHz . A low-noise $10-\mathrm{GHz}$ HEMT may well have a higher noise figure at 432 MHz than a much less expensive device specified for operation through 4 GHz . This is why so many Amateurs have been able to demonstrate incredibly low noise figures on 2 meters using GaAsFETs costing no more then $\$ 5$ to $\$ 10$ !

Also, the higher the cutoff frequency of a GaAsFET or HEMT, the narrower the gate; hence, the susceptibility to static burnout increases. Furthermore, higher frequency devices are more prone to oscillate when operated at lower frequencies. So don't "read into the specifications' anything that isn't there. For optimum performance versus cost, operate MESFETs in the frequency range recommended by the supplier.

## noise figure limitations

I'm often asked the question, "What limits noise figure?" It should be intuitive that part of the limitation on noise figure is in the actual device itself. Furthermore, for the lowest possible noise figure in a receiver, the gain of the first stage must be high and the second stage should also have a low
noise figure. This is shown mathematically by the following equation.?

$$
\begin{gather*}
F=F_{1}+\left(F_{2}-I / G_{l}\right)+  \tag{1}\\
\left(F_{3}-1\right) /\left(G_{l} \cdot G_{2}\right)+\cdots
\end{gather*}
$$

where $F$ is the overall noise factor of the receiver, $F_{1}$ is the noise factor of the first stage, $F_{2}$ is the noise factor of the second stage, $F_{3}$ is the noise factor of the third stage, $\mathrm{G}_{1}$ is the numeric gain of the first preamplifier and $\mathrm{G}_{2}$ is the numeric gain of the second preamplifier. Note that noise factor and gains are in numerics, not decibels, so they often have to first be converted from decibels to numeric values before using them in eqn. 1. After the final noise factor is determined, you'll probably want to convert noise factor back to noise figure using the following equation.

$$
\begin{equation*}
N F=I 0 \log F \tag{2}
\end{equation*}
$$

For example, refer to fig. 3, a block diagram of a typical Amateur front end. In example 1, if the noise figure of the first stage of a receiver is 0.5 dB (noise factor $=1.122$ ), with a gain of 13 dB (gain $=20$ ) and the second stage noise figure is 4.0 dB (noise factor $=2.51$ ), with a gain of 15 dB (gain $=31.6)$-- ignoring the third stage contribution and assuming it to be negligible) - the overall receiver noise figure will be 0.78 dB (noise factor $=$ 1.197), a significant $0.28-\mathrm{dB}$ increase over the first stage alone.

Now if we reduce the noise figure of the second stage to 1.75 dB (noise factor $=1.496$ ) [example 2 ] or increase the gain of the first preamplifier to 8 dB (gain $=63$ ) [example 3], the overall noise figure will be 0.59 dB (noise factor $=1.46$ ), only 0.09 dB above the preamplifier alone, a small penalty to pay.

These calculations are often laborious and prone to error. For this reason, it's best to program eqn. 1 and eqn. 2 into a computer or scientific calculator to simplify the calculations and decrease the possibility of human error. ${ }^{8}$

Finally, don't get carried away with gain. Increasing the first stage gain too much may lead to intermodulation distortion or instability, thus limiting the

ability to use the inherent low noise figure. ${ }^{9,10}$ Therefore, with the low cost of devices today, it's preferable to design for a reasonable first stage gain ( 15 to 20 dB ) and use a similar type second stage with a moderate noise figure ( 1.0 to 2.0 dB typical). This provides an inexpensive and useful cost/performance tradeoff.

## other noise figure limitations

Another noise figure limitation is incurred by operating a preamplifier at room temperature (more on this shortly). However, the major limitations on Amateur receivers attaining very low noise figures commensurate with device specifications are losses associated with the input impedancematching circuitry.

Amateur preamplifiers are usually designed for a single frequency band. Typically the circuits employ some form of input tuning. This is a preferred technique since the input network will not only allow the device to be optimized for the lowest possible noise figure at the frequency of interest, but will also act like a filter and prevent strong out-of-band signals from entering or causing IMD.

Most Amateur preamplifier input circuits, especially below 500 MHz , use an inductor and capacitor tank circuit similar to those shown in figs. 4A and 4B. Figure 4A has one less component, but it also requires the tap to be


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fig. 4. Some typical recommended input matching circuits for Amateur low-noise GaAsFET preamplifiers operating below 2.5 GHz : (A) tapped inductor; (B) capacitor transformer; (C) lossless feedback.
carefully chosen. This can be very tedious and time-consuming, especially if you want to achieve minimum noise figure. Therefore, the input impedancematching circuit shown in fig. 4B is recommended for 500 MHz and below. ${ }^{1}$

Sometimes I see Amateurs and commercial designers alike using an abbreviated type of input matching similar to that shown in fig. 4B, but with the shunt capacitor, C2, removed. This is not recommended because if the lowest possible noise figure is wanted, the inductor also has to be
tuned, and that can be a tricky job. (And what do you do for tuning if the GaAsFET has to be replaced?)

By now you've probably surmised that the minimum noise figure isn't only a function of tank circuit alignment, but more likely due to losses in the components themselves. All capacitors and inductors have loss, especially as you go above 100 MHz . The higher the $Q$ of the components in the input-matching network, the lower the insertion loss and hence the lower the noise figure.

Probably the "lossiest" component in a low-noise preamplifier is the inductor. A typical inductor in the 100 - to $500-\mathrm{MHz}$ range has an unloaded $Q$ (no external components attached) of 300 to 500 , depending on wire type, diameter, form factor, and proximity of other components and shielding structure. ${ }^{11}$

As explained in reference 11, there's a definite insertion loss relationship between the unloaded $Q_{U}$ of an inductor and the loaded or "in-circuit" $\mathrm{Q}_{\mathrm{L}}$ of the same as follows:

$$
\begin{gathered}
\text { insertion loss }(d B)=10 \log \\
{\left[I-\left(Q_{L} / Q_{U}\right)\right]^{2}}
\end{gathered}
$$

where $Q_{L}$ and $Q_{\mathrm{U}}$ are the loaded and unloaded $Q s$ s, respectively.

How do you determine the loaded $Q$ of the inductor? If the preamplifier is one of the types that uses a broadband output network as described in reference 1 , the half-power or $3-\mathrm{dB}$ bandwidth of the preamplifier can be easily measured. The $Q$ of the preamplifier (and therefore the loaded $Q$ of the inductor) is then determined as follows:

$$
\begin{equation*}
Q \text { preamp }=f_{o} /\left(f_{H}-f_{L}\right) \tag{4}
\end{equation*}
$$

where $f_{O}$ is the center frequency in $\mathrm{MHz}, f_{H}$ is the upper half-power frequency and $f_{L}$ is the lower half-power frequency. For example, if we have a $432-\mathrm{MHz}$ preamplifier with half-power frequencies of 440 and 423 MHz respectively, the loaded $Q$ will be $432 /(440-423)$ or 25.4 .

Now, if we assume that all other components contribute negligible loss, we can determine the approximate in-
put circuit losses attributable to the inductor's $Q$. Using eqn. 3 and assuming a good inductor with an unloaded $Q$ of 500 and a preamplifier with a loaded $Q$ of 25.4, we have an input circuit insertion loss of approximately 0.45 dB .

Typical GaAsFET preamplifiers using input tank circuits of this type have noise figures of 0.5 to 0.75 dB . Therefore, with a $0.45-\mathrm{dB}$ input loss, the overall noise figure of the preamplifier is almost entirely due to the losses in the input network and the GaAsFET itself must be virtually noiseless!

To show the $\mathrm{Q}_{U} / \mathrm{Q}_{\mathrm{L}}$ losses more graphically, I've prepared the graph in fig. 5 and scaled it for low loss and hence low noise figure conditions. (Check fig. 5 for the $432-\mathrm{MHz}$ preamplifier case above.) For a $Q_{U} / Q_{L}$ ratio of $500 / 25.4$, or approximately 20 , you'll see that the insertion loss is indeed 0.45 dB .

Also note in fig. 5 that to get the input losses down below 0.1 dB , the unloaded-to-loaded $Q$ ratio must be equal to or greater than 90 . This means that the unloaded $Q$ of the inductor in the preamplifier just described would have to be over 2000! If you want a very low-noise preamplifier, you're going to have to use some pretty lowloss inductors - such as a large (1- to 3-inch diameter) coaxial cavity resonator - and possibly have them silver plated.

Figure 4C is a different input circuit topology which eliminates the tank circuit per se by using a series input inductor and "lossless feedback" in the source lead.' This type of circuit definitely has lower input losses and potentially a better input VSWR. However, it's more prone to out-of-band interference and therefore is more appropriate for use on the microwave bands. It will be discussed further in next month's column.

## other component losses

Don't forget that there can be other losses besides the input inductor. Tuning capacitors can also have losses. Only the lowest loss, highest $Q$ tuning capacitors should be used in the

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input-matching network. The air-variable type capacitors manufactured by Johanson and others are a preferred type. They not only have low loss and high $Q$, but also good tuning resolution with little or no backlash. Furthermore, they often have special sealing caps that can be placed over the tuning mechanism to help keep out moisture and prevent inadvertent mistuning.

The minimum $Q$ of a Johanson-type 5200 air variable, one commonly used by Amateurs, is 5000 at maximum capacitance at 100 MHz . This figure decreases rapidly to less than 1000 above 300 MHz ! Higher $Q$ types such as the Johanson 5700 and 5800 are recommended, but they have lower maximum capacitance so they're useful only for higher frequencies and for series connections where lower capacitance values are required.

Chip capacitor losses can also be considerable, especially when used in source bypassing or in the rf path. In critical low-loss circuits, the porcelain types are highly recommended despite their higher initial cost. Be careful, too, of resistor types. The older $1 / 8$ or $1 / 4$-watt carbon composition types are recommended. However, the noncarbon or film types that are becoming so popular are usually quite reactive and lossy, and are therefore not recommended.

Finally, coaxial connectors - especially type N, TNC, and SMA ... are highly recommended for low-noise preamplifiers because they have low loss and a very positive mating mechanism. On the other hand, BNC- and UHFtype connectors should be avoided because their impedance isn't constant, and they have questionable mating

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| MRF248 | 80W | 136-174 | 33.00 | 71.00 |
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tolerances and known insertion losses. Connector types and losses are discussed further in references 12 and 13.

## lower noise techniques

Cooling is probably the last resort when it comes to really low-noise preamplifiers. Bipolar transistors generally don't work well below about 70 to 80 degrees Kelvin. However, many GaAsFETs and HEMTs seem to do quite well when cooled even as low as 12 degrees Kelvin, the temperature of liquified Helium.

The National Radio Astronomy Observatory (NRAO), in Charlottesville, Virginia, has been building lownoise preamplifiers for many years. Their preamplifiers are used in radio telescopes where the sky temperature is as low as 3.5 degrees Kelvin, almost absolute zero. By 1980 they were using GaAsFET preamplifiers cooled to about 13 degrees Kelvin in a Dewar with liquified Helium. ${ }^{14}$

At first NRAO used GaAsFETs because they noticed that the transconductance would often increase sometimes by as much as 50 percent - as temperature was decreased. At the same time, the noise figure would drop. However, the optimum source impedance changes at low temperatures and oscillations may occur. Consequently the preamplifier has to be optimized at the cold temperature. Recently, NRAO noticed the same effects with HEMTs.

Because the cryogenic coolers used by NRAO cost about $\$ 5000$ each, they're not really practical for Amateurs. Other less expensive coolers such as the thermo-electric type are available commercially. ${ }^{15}$ However, they use diodes that may generate noise, so be cautious if you use them. It should be sufficient to mention that if you have an antenna-mounted preamplifier, especially for EME, you should mount it so that it won't be heated excessively by the sun.

Finally, of the GaAsFETs tested by NRAO, the MGF 1412 seems to have consistently low noise figure at room temperature. Futhermore, at cryogenic temperatures, the MGF 1412 type
seems to be one of the most reliable for low noise figures. Since this is one of the most popular types used by Amateurs seeking the lowest possible noise figures, it may be a place to start.

## summary

In this month's column, I've attempted to bring you up to date on the SOA in low-noise receivers for VHF and above. Noise figures are still dropping, but at some frequencies can't go lower unless we change the circuit techniques we're presently using. In next month's column, we'll discuss some circuit and device recommendations.

## acknowledgments

I'd particularly like to thank Bill Lakatosh, AA4TJ (ex K3QCO and KJ4OI), of NRAO for their input on SOA noise figures and cooling techniques.

## new records

In last month's column we mentioned the outstanding sporadic E occurrence during the ARRL June VHF OSO party and asked for any new record claims. Shortly after the contest was over, I received and authenticated a new North American 2-meter, doublehop sporadic E record. The new record holders are Jim Poore, KD4WF, in Savannah, Georgia (EN92LK) and Jim Frye, NW7O/7, operating portable from Mount Potosi, southern Nevada (DM25GV). Their contact took place on June 14, 1987, at 1704 UTC and extended the existing record by almost 90 miles for a new record of 1980 miles ( 3186 km ). Congratulations to both Jims.
The North American $10-\mathrm{GHz}$ DX record has also been broken; more on that in next month's column.

| important VHF/UHF events |  |
| :--- | :--- |
| November 3 | Predicted peak of <br> the Taurids <br> meteor shower at |
| November 3 | 2200 UTC <br> Predicted peak of <br> the Cassiopids <br> meteor shower at <br> 2200 UTC |

November 14-15 ARRL EME Contest (second weekend)
November 17 Predicted peak of the Leonids meteor shower at 1500 UTC
November 21 New moon
November 24 EME perigee
December 13 Predicted peak of the Geminids meteor shower at 1900 UTC
December 20 New moon
December $21 \pm$ month. Winter
peak of sporadic $E$ propagation
December 22 Predicted peak of the Ursids
meteor shower at 2200 UTC
December 22
EME perigee

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## AEA weather FAX mod for the PK-232

Over the past few years, packet radio has grown from a rather esoteric part of Amateur Radio to one of the fastest growing segments ever. There must be at least ten manufacturers of TNCs, all selling basically the same product.

One way of selecting a TNC is to look closely at the features each unit offers. Do you want to go beyond packet? How about RTTY, AMTOR, ASCII, CW and weather FAX (WEFAX)? How

about SIAM, Signal Identification and Acquisi tion Mode? If you want all these features in a single unit, your only choice is the AEA PK-232.

All currently manufactured PK-232s have the FAX and SIAM option installed. The unit we reviewed earlier (see page 81 of the July, 1987 issue) was one of the first units off the line and needed to be modified to work on WEFAX and SIAM.

When I learned of AEA's modification for WEFAX, I immediately called and placed an order for the kit. Because demand was enormous, it took a few weeks for my kit to arrive.

Besides the parts and instructions needed to perform the mod, AEA also supplied an addendum for the operator's manual and a pre-made computer-to-TNC to printer cable. The cable alone is more than worth the $\$ 40$ price of the modification kit.

AEA is currently supporting most parallel graphics, and your dealer will have a complete list of printers that AEA has tested with the PK-232.

Four simple steps were all that were required to make the modification: remove the unit from use, disconnecting all cables; prepare a clean, static-free work area; remove six screws and open the unit; remove and replace EPROM U2 and install EPROM U3, then screw the cover back on. That's all there is to it. You're ready to reconnect and get back on line.

Sometimes it's hard to believe that the EPROM is as powerful as it is. Without EPROMS, the unit can't operate. Yet they can be installed in less than a heartbeat.

## operation

I'll break this section into two parts: WEFAX and SIAM.
WEFAX. While WEFAX is basically a service for ships and aircraft, it offers a wealth of information for amateur meteòrologists too. Stations transmit weather maps that show actual conditions and prognostications, satellite photographs of the earth's surface, taken from geosynchronous and orbiting satellites, and plenty of additional information. Of particular interest to me has been the hurricane maps that are sent during the hurricane season here on the East Coast.

Transmitting stations are located around the world, with each transmitting information for its own geographical area. Here in the Northeast, Halifax, Canada and Norfolk, Virginia provide the most reliable reception and information. I haven't had much luck with European or West Coast stations, but this is more a problem of time on the air and propagation.

The PK-232 represents the third generation of WEFAX equipment I've operated. Of the three units I've used, it's by far the easiest to set up and the most convenient to use. No special paper is required. There are no noxious fumes, the unit is easy to transport and install - it's really a pleasure!

From the time the modifications were finished, the cables installed, the computer hooked up and

## REVIEW

booted, to the reception of the first pictures, a grand total of 15 minutes passed.

Because you're using a dot matrix printer, you can't resolve shades of gray and therefore can't reproduce satellite images with pure photographic quality. The images, however, are very good and quite usable. Since maps and charts are black on white, their reproduction quality is excellent.

All you need to do is tune to a station transmitting FAX (with digital readout radios, tuning the PK-232 is no more complicated than subtracting 1.7 kHz from the transmitting station's published frequency). That's a heck of alot easier than it was with the old Hammerlund HQ-110's "coarse" and "fine" tuning controls. Then just configure the PK- 232 to FAX mode, turn on the printer, and Bingol Out come the maps and charts you've been waiting for.

You can also transmit FAX pictures. Frankly, because transmitting $F A X$ requires a special program, I didn't try this option, so I can't comment on the PK-232's capabilities in this area. AEA is currently developing an MS-DOS program for FAX transmission. Details are too sketchy to report. However, early versions include FAX display on screen, transmission capabilities, and a number of other features. Availability is scheduled for late fall or early winter.
SIAM. One of the first things you notice when you tune across the hf bands is the variety of different digital signals. Even if you were an expert and could tell by sound alone, it would take time to configure the PK-232 to receive these signals. With SIAM, the PK-232 analyzes the signal and identifies the type of transmission and its speed. The operator can then decide whether to receive the station or continue on with a band search.

SIAM will decode a number of different digital codes: ASCII, ARQ, and FEC AMTOR and Baudot. It will also decode the Russian Cyrillic and Japanese Katakana codes.

To use SIAM, all you do is type in the command OPMODE SIGNAL, confirm that the receive (DCD) LED is lit, and wait approximately 10 seconds. The PK 232 will respond with a baud rate indication and a confidence of mode factor. In another 15 seconds, the PK- 232 will identify the signal. To copy the signal, all you do is type in the command $O K$. If the SIAM analysis is correct, you'll start seeing text. If not, the PK. 232 will give you a ?bad prompt.

If the text is decoding but seems to be encrypted, you can try setting BITINV to 0 through 31, if only simple bit-inversion encryption is being used. If none of these 32 settings will decode the station, chances are another more sophisticated encryption system is being used.

## conclusion

Typically, AEA has included a well written owner's manual that describes the operation of both WEFAX and SIAM modes fully. In case of difficulty, AEA has listed a number of common faults and the appropriate fixes. They also offer excellent advice by telephone if the manual and a little bit of work fail to solve the problem.

If you have a PK-232 and haven't yet modified it, you're missing out on a treat. I wouldn't just walk - I'd run to place the order!

AEA, 2006 196th Street SW, Lynnwood, WA 98036.

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## miniaturized DTMF encoders

Pipo Communications has introduced the $\mathrm{P}-7$ and P-8 series of miniaturized DTMF encoders designed for custom installation in radios or systems that are exposed to harsh or abusive environments. Built with steel keys and sealed gold dome contacts to ensure reliability and long life, the P-7 and P-8 encoders will fit most radios.


The P-7, a 12 -key touchtone encoder, comes in vertical ( $\mathrm{P}-7 \mathrm{~V}$ ) or horizontal ( $\mathrm{P}-7 \mathrm{H}$ ) formats measuring 2.16 inches by 1.5 inches by 0.20 inches. The P-8, a 16 -key touchtone encoder, is available in a vertical (P-8V) format only; it measures 2.16 inches by 1.9 inches by 0.20 inches. Both are available in black or dark brown.

For more information, contact Pipo Communications, P.O. Box 2020, Pollock Pines, California 95726-2020.

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In addition, the 10PS 101 features a bi-directional noise filter to eliminate both RFI and EFI interference. The noise filter functions over a broad band ( 100 KHz to 20 MHz ); high frequency signals in this range are attenuated by up to 30 dB for improved equipment performance.
UL-listed and American-made, the 10PS101 has six NEMA-type plug-ins and a heavy-duty.

three-wire grounded 6 -foot power cord. MOV working status is confirmed by a built-in indicator lamp.

For more information, contact TDP Electronics, 111 Old Bee Tree Road, Swannanoa, North Carolina 28778.

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## all-mode $440-\mathrm{MHz}$ base station transceiver

ICOM has introduced the IC-475A $440-\mathrm{MHz}$ base station transceiver. This deluxe all-mode base receives from 430 to $450-\mathrm{MHz}$ and has 99 tunable full-function memories, passband tuning, a notch filter, noise blanker, built-in SWR bridge, semi or full CW break-in, and a multifunction meter. The new IC-475A also has a velvet-smooth tuning knob and easy-to-read amber LCD readout with variable backlight.


Four scanning systems are available: band, programmable, mode, and memory scan that scans 99 memories in five seconds, with selectable lock-out. The IC-475A features exciting new options such as a tone squelch unit, speech synthesizer, and OSCAR module that allows tracking with a companion IC-275A or IC275H;

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call Randy（205）832－4598 or Ken（205） $271-0028$.

COLORADO：November 29．The Denver Radio Club＇s an nual Hamfest and ARRL State Convention，Jefferson County Fairgrounds，6th Avenue and Indiana，Goiden． 9 AM 2 PM．Swap tables，seminars，code contests．Non and 146．52．Contact Dean Haworth，ACOS（303）279－4956 for more information．

FLORIDA：November 21 and 22．South Florida ARRL Suncoas Convention sponsored by the Florida Gulb Coast ARC Council St．Petersburg Hilton and Towers．Hugh flea market．Amateur exams．Saturday OCWA luncheon．Tech talks and demos tion information write FGCARC， 1556 －56thAvenue North，St tion information write
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WISCONSIN：November 14．The Milwaukee Repeater Club is sponsoring the third annual＂ 6.91 Friendly Fest＂，Serb Hall， 51 s sponsoring the third annual＂ 6.91 friendly Fest，Serb Hall， 1 ll ，
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MASSACHUSETTS：November 21．The Honeywell Bull 1200 Radio Club and the Waltham Amateur Radio Association will hold their annual Amateur Radio and Electronics Auction， Honeywell Bull plant， 300 Concord Road，Billerica．Snack bar and bargain parts store．Doors open 10 AM．Free admission and parking．Talk in on 147．72／12 and 146．04／64 repeaters．For in－ formation：Doug Purdy，N1BUB， 3 Visco Road，Burlington，MA 01803

GEORGIA：October 31 and November 1．Ham Radio \＆Com－ puter EXPO 87 sponsored by the Alford Memorial Radio Club puter ExPO 87 sponsored by the Alford Memorial Radio Club． Atlanta．VEC exams both days，covered flea market，free park ing，RV sites with hookups，convenient lodging．\＄5 admission includes Saturday night cookout．For more information：EXPO ＇87．POB 1282，Stone Mountain，GA 30086

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OHIO：November 22．The Massillon ARC will sponsor AUC TIONFEST＇87，Massillon K of C Hall，off Rt 21． 8 AM to 5 PM Sellers setup 7 AM．Admission $\$ 3.50$ advance and $\$ 4 /$ door． Tables available $\$ 7 / 8^{\prime}$ space．Refreshments available．Free park ing．Auction starts 11 AM．Talk in on W8NP，147．78／．18．For advance registration and information SASE to MARC，POB 73 ， Massillon，Ohio 44646.

## OPERATING EVENTS

## ＂Things to do

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Tom McMullen, W1SL

## receiver buzzwords

Because this is the annual receiver issue, I'll try to clarify some receiverrelated terms you might be wondering about. Who knows? This information might even help you choose a rig from among the many available.
One of the biggest problems an Amateur faces is interference from other signals, so l'll emphasize techniques that help reduce that problem.

RIT stands for Receiver Incremental Tuning, a way of tuning the receiver without disturbing the transmitter frequency. This feature is useful if the station you're listening to drifts slightly, or if you have to tune just a wee bit off frequency to minimize the effects of interference. In the earlier days of single-VFO transceivers without RIT, when you moved your receiver dial you also moved your transmitter. The other station then had to move to tune you in. Then you'd move again - and so on. This led to the two stations "walking" each other across the band; if they weren't careful, they could wind up out of bounds. With RIT, you can leave the transmitter alone and move the receiver a few Hz to keep the other station tuned in.

A direct conversion or single conversion receiver is perhaps the simplest type of heterodyne receiver in use. It's basically a local oscillator (usually a very stable VFO) and a balanced mixer. The rf signal and the

VFO are both fed into the mixer, and when the two frequencies are the same (zero-beat with each other), any audio present on the rf signal becomes a product of the mixing process. This audio is fed to audio amplifiers to drive a headset or a speaker, as needed. An rf amplifier is often used ahead of the mixer, and an audio filter after the mixer to prevent hearing the beat notes produced by nearby signals. Many low-power or portable stations use this type of receiver because of its simplicity, light weight, and low power requirements. While direct conversion isn't directly related to interference problems, it's worth knowing about this type of receiver in order to understand other discussions to come.

If a single-conversion receiver converts once - from rf to audio frequencies - then it follows that a double-conversion receiver converts twice. The first conversion mixes an rf signal with the first local oscillator, which produces an intermediate frequency signal, abbreviated $i-f$. (Notice the hyphen; it's there so you'll know not to read " $\mathrm{i}-\mathrm{f}$ " as the word "if.")

The second conversion mixes the i-f signal with a second local oscillator to produce . . . Uh, here's where our nice, neat scheme falls apart!

Older receivers, designed to handle amplitude modulation (a-m), used a diode detector at the end of the i-f amplifier circuit. The second local oscillator would produce another i-f
signal, which would then be detected by a diode, to produce audio, etc. In this case, it's a double-conversion receiver. However, newer receivers, designed to handle single-sideband (SSB) signals, needed a different arrangement. Diode detectors are practically useless for SSB detection, so a circuit called a product detector, amazingly similar to the single-conversion scheme I mentioned earlier, was developed. This circuit includes a local oscillator that mixes with the i-f signal to produce audio output. The product detector works well with a-m and CW, and really shines with SSB signals.

So whether a receiver is double or triple conversion really depends on the definition of the detector circuit. For example, a receiver that uses a VFO to produce an i-f of, say, 9 MHz , and then a second oscillator and mixer to produce a lower i-f at, perhaps, 455 kHz , which is followed by a diode detector, is clearly a double-conversion receiver.

Does changing the diode detector to a product detector make the receiver triple conversion, then? The purists will say yes, but many manufacturers just don't mention it. (And it really isn't important unless you need to know the definition in order to prove a point!)

Double-conversion receivers are important, however, in solving image problems. To follow me through this one, image rejection, you'll need to look at fig. 1 and check the arithmetic.

fig. 1. Image rejection is often poor in receivers with a low-frequency $i-f$, as at $A$. When the first $i-f$ is high, the image moves away from the receiver front-end response, shown at $C$.

If the signal you wanted to listen to was the only one on the band, life would be simpler. But there are plenty of signals out there, and most of them aren't the ones you want to hear. A simple receiver (such as a singleconversion type) is capable of receiving all sorts of things you don't want, many of them signals that aren't in the Amateur bands. Let's say you want to tune in a signal at 28.205 MHz . Your i -f is 455 kHz , so your VFO is at 27.750 . This produces the right i-f, but if there's a loud signal at 27.295 (as there often is), it too can mix with the VFO to produce 455 kHz .

This intruder is called the image signal. An interesting thing is that the image signal is always twice the first i-f away from the signal you want. In the case above, $2 \times 455=910$, and $28.205-0.910=27.295$. If you know that, you can track down suspected image interference.

How do you get rid of it? There are a couple of common tricks: one is to place the VFO above the signal - at 28.660 to receive 28.205 MHz , for example. This would place the image at 29.115, which means that the signal would be from an Amateur station but that's not much help if it buries your QSO.

A more practical method is to use
a double-conversion receiver and make the first $\mathrm{i}-\mathrm{f}$ high - perhaps $9,10.7$, or even 70 MHz . The high i-f places the image quite some distance away from where the receiver front end is tuned, and it's easier for simple tuned circuits to reject a signal that's far removed from its design frequency. For instance, a $10.7-\mathrm{MHz}$ i-f will place the image of 28.205 at 49.605 MHz , as shown in fig. 1. Even a mediocre front end can reject that one.
Another common cure is to build filters (special tuned circuits) that pass only a narrow range of frequencies, say from approximately 27 to 31 MHz for the 10 -meter band, but greatly attenuate anything outside that range. Many modern solid-state receivers use this technique on all bands, along with broadband if amplifier sections, to provide good performance and require minimum attention from the oderator.
SINAD isn't a remedy for sinus trouble; it's a test commonly used to determine how well a receiver hears a weak signal. SINAD is an acronym for signal + noise + distortion to noise + distortion ratio. (Aren't you glad they shortened it?) This is what it means:
If you disconnect the antenna from your receiver and turn the audio gain up, you'll hear a hiss or rushing noise.

That's the "noise" part of the formula. It takes a certain amount of signal strength to be heard through that noise. The level of that signal is the "signal" part of the formula. The "distortion" part comes in because a signal can be loud but not clear.

The signal generator used for this test is modulated, and the recovered audio from the receiver is compared with the modulation waveform to see if it has been distorted - and usually, it has. Thus, the test will determine how strong a signal it takes to produce some specific output above the noise, and how badly the i-f filters, audio amplifiers, and even the power supply hum have distorted the audio output.

Fortunately for us, the test results are neatly summed up on a meter on the test equipment, and we don't have to spend a lot of time calculating ratios and such. The test instrument, naturally enough, is called a SINAD meter.

The usual method of rating a receiver under this test is to state a signal strength that's required to meet a particular dB SINAD ratio: for example, $0.5 \mu \mathrm{~V}$ for $12-\mathrm{dB}$ SINAD. The lower the microvolt ( $\mu \mathrm{V}$ ) number, the better the receiver, and 12 dB is an industrywide benchmark used in the test.

An i-f notch filter lor i-f notch tuning) is another device used to
reduce the effect of interference. It consists of a high- $Q$ circuit that works within the "window" or passband of the i-f amplifier. Instead of acting as a bandpass device, however, it's a band-stop circuit designed to attenuate greatly whatever frequency it's adjusted for. This is most useful if you're listening to a weak signal (or even a moderately strong one) and someone pops up close enough to create an earsplitting whistle or lots of "splatter" on top of the signal you want to hear. By adjusting the i-f notch, you can often reduce the commotion to a level you can live with.
An i-f notch filter will have limited usefulness, however, because any notch deep enough to really eliminate an interfering signal will also reduce the strength of the signal you want to hear.
Interference suppression can also be handled by an audio filter that cuts off all audio tones outside a narrow range. This is great for CW signals, but voice (SSB) tends to sound hollow and distorted if the audio passband gets too narrow. There is an equivalent to the i-f notch filter called the audio-notch filter or audiorejection filter. A piece of electronic trickery that uses op amps to create a phase shift that will cancel the offending tone, it works quite well, and usually consists of one or two integrated circuits, a potentiometer or two, and a few resistors and capacitors. Both the frequency of rejection and the degree of rejection (depth of the notch) are adjustable. The audio-notch filter is a great add-on for directconversion receivers.
Another neat bit of electronic sleight-of-hand is i-f shift. It takes some of study to figure out how it works, but it's really quite simple. In essence, it works this way: when a signal is in the same i-f passband as the one you want to hear, you just move the passband "window" over a bit until that signal is outside it. You can do the same thing by slowly tuning your receiver until the interference is out of the passband, but when you do that, the signal you want is moving also,

fig. 2. I-F shift, or i-f tuning, can move an interfering signal out of the i-f passband, then place the wanted signal back in the low-freqency i-f window for clear reception. This example uses approximately $8 \mathbf{M H z}$ for a passband filter, then converts down to a conventional 455kHz i -f for further amplification and detection.
and might end up as a tone that's not easy to hear (on CW) or as duck-talk (on SSB).

Perhaps fig. $\mathbf{2}$ will help clarify this. At $A$, both the interfering signal and the wanted signal are in the i-f passband. By adjusting the i-f shift, you can move the interfering signal out of the passband, as at B, and leave the wanted signal in. Now, the only trick is to get the wanted signal back into the center of the window again, as at C.

How do they do that? By adding two more conversions in the i-f amplifier chain, and using the same beatfrequency oscillator (BFO) to mix with the signal twice. For example, you can mix a $455-\mathrm{kHz}$ signal with an $8.0-\mathrm{MHz}$ BFO to produce an 8.455 i -f. This i-f signal then passes through a filter and into another mixer. There, the 8.455MHz signal mixes with 8.0 to produce the original 455 kHz i-f again.

Now to exercise the cranium a bit more - with the help of fig. 2 - and get more specific: let's say that the signal you want comes through the i-f amplifiers at $455,000 \mathrm{~Hz}(455 \mathrm{kHz})$. The one that's bothering you comes through at $455,500 \mathrm{~Hz}$. This produces the normal result at $\mathbf{A}$, with both signals inside the i-f passband. By detuning the $8.500-\mathrm{MHz}$ VFO a few Hz to 8.499, and mixing with the i-f signals, you can change the wanted signal to 8.044 , and the interference is at 8.0435 MHz , as shown at B.

The $8-\mathrm{MHz}$ i-f filter will pass 8.044 , but not 8.0435 , so the interference is gone! When 8.044 is again mixed with 8.499, the difference is 455 kHz , which is right back in the middle of your i-f window (at C), just where you want it.

Of course, this is a greatly simplified example of how it works, and l've made the frequency separations large to make the example easier to follow, but you get the idea. Many manufacturers use more complex circuits to accomplish this, and some use phaselocked loop (PLL) circuits to move the signals around and reject the unwanted ones. No matter how they do it, the results make it worth looking for this feature in a receiver.

## conclusion

The degree of interference rejection you need depends upon the type of operating you do. On most of the hf bands, crowding is a way of life, and the best DX is usually buried beneath several layers of loud signals. It seems to be magic when an experienced operator can peel away those layers to leave an S1 or S2 signal standing alone, perfectly readable among $\mathrm{S} 9+$ "locals." By carefully choosing your interference-fighting weapons, and with some practice, you too can become a magician.

Next month, l'll explore the possibilities of 1200 MHz .
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